#### REGULATION

## OF THE MINISTER FOR INFRASTRUCTURE 1)

of ... 2023

# on the type approval of trams and trolleybuses<sup>2), 3)</sup>

Pursuant to Article 55(1) of the Act of 14 April 2023 on the approval systems of vehicles and their equipment (Journal of Laws, item 919), the following is hereby decreed:

# **§ 1.** The Regulation lays down:

- the scope of the technical requirements applicable to the national type approval procedures for trams and trolleybuses and the detailed method of carrying out these procedures;
- 2) the detailed activities of the Director of Transportation Technical Supervision, hereinafter referred to as the 'Director of TDT', and of the technical services in the national type approval procedure for trams or trolleybuses;
- 3) the conditions and method of selecting a tram or trolleybus for approval tests;
- 4) the scope and method of conducting type approval tests by the technical service and control of conformity of production in connection with the national type approval procedure for trams or trolleybuses;
- 5) model documents used in the national type approval procedure for trams or trolleybuses;
- 6) a model of approval mark and a method of numbering national type approval certificates for trams or trolleybuses.

<sup>&</sup>lt;sup>1</sup> The Minister for Infrastructure manages the government administration department for transport, pursuant to § 1(2)(2) of the Regulation of the Prime Minister on the specific scope of activities of the Minister for Infrastructure of 18 November 2019 (Journal of Laws of 2021, item 937).

<sup>&</sup>lt;sup>2</sup> This Regulation serves to apply Regulation (EU) 2018/858 of the European Parliament and of the Council of 30 May 2018 on the approval and market surveillance of motor vehicles and their trailers, and of systems, components and separate technical units intended for such vehicles, amending Regulations (EC) No 715/2007 and (EC) No 595/2009 and repealing Directive 2007/46/EC (OJ L 151, 14.6.2018, p. 1, OJ L 325, 16.12.2019, p. 1, OJ L 19, 21.1.2021, p. 2, OJ L 272, 30.7.2021, p. 16, OJ L 313, 6.9.2021, p. 4, OJ L 398, 11.11.2021, p. 29, OJ L 187, 14.7.2022, p. 19, and OJ L 296, 16.11.2022, p. 1).

The notification of this Regulation was made to the European Commission on ..., under No ..., pursuant to § 4 of the Cabinet Regulation of 23 December 2002 concerning the manner in which the national notification system of standards and legal acts functions (Journal of Laws, item 2039, and of 2004, item 597), which implements the provisions of Directive (EU) 2015/1535 of the European Parliament and of the Council of 9 September 2015 laying down a procedure for the provision of information in the field of technical regulations and of rules on Information Society services (OJ L 241 of 17.9.2015, p. 1).

- § 2. Terms used in this Regulation shall be understood to mean:
- 1) Regulation (EU) 2018/858 Regulation (EU) 2018/858 of the European Parliament and of the Council of 30 May 2018 on the approval and market surveillance of motor vehicles and their trailers, and of systems, components and separate technical units intended for such vehicles, amending Regulations (EC) No 715/2007 and (EC) No 595/2009 and repealing Directive 2007/46/EC (OJ L 151, 14.6.2018, p. 1, as amended<sup>4)</sup>),
- 2) Act the Act of 14 April 2023 on approval systems for vehicles and their equipment (Journal of Laws, item. 919);
- § 3. 1. The scope of the technical requirements applicable to the national type approval procedure:
- 1) for trams, are set out in:
  - a) the provisions on the technical conditions of trams and trolleybuses and the scope of their necessary equipment pursuant to Article 66(5) of the Road Traffic Act of 20 June 1997 (Journal of Laws of 2023, items 1047, 919 and 1053),
  - b) the provisions of the UN Regulations listed in Annex 1 to the Regulation setting out the list of the required UN Regulations applicable to type approval of trams;
- 2) for trolleybuses, are set out in:
  - a) in the part relating to electrical traction equipment and its control system and electrical auxiliary circuits powered directly or indirectly from the overhead contact line, the provisions issued pursuant to Article 66(5) of the Road Traffic Act of 20 June 1997,
  - b) for the remainder, the provisions of Regulation 2018/858 and the delegated and implementing acts issued pursuant thereto.
  - 2. The requirements set out in paragraph. 1 shall apply to:
- 1) trams of which:
  - a) type includes vehicles for which all of the following features are common:
    - manufacturer,
    - factory type designation,

<sup>&</sup>lt;sup>4</sup> Amendments to the said Regulation were announced in OJ L 325, 16.12.2019, p. 1, OJ L 19, 21.1.2021, p. 2, OJ L 272, 30.7.2021, p. 16, OJ L 313, 6.9.2021, p. 4, OJ L 398, 11.11.2021, p. 29, OJ L 187, 14.7.2022, p. 19 and OJ L 296, 16.11.2022, p. 1.

- main design considerations, including:
  - -- the design of the body (obvious and basic differences),
  - -- main traction drive (electric mains or autonomous electric),
  - -- number of tram sections,
- b) variant includes vehicles for which all of the following design features are common:
  - type of tram (motor, active trailer, passive trailer),
  - directionality of the tram (uni-directional or bi-directional),
  - nominal supply voltage,
  - track gauge,
  - bogies or chassis (essential design features),
  - driving axles (number, position, kinematic link),
  - axle arrangement,
  - type and sort of electric traction motors (DC, asynchronous or synchronous),
  - number of motors and traction converters,
  - type and sort of traction converters,
  - type and sort of braking systems (electrodynamic, track, disc, shoe or eddy current retarders),
  - type of autonomous driving system (battery, capacitor or capacitor with batteries),
- c) version includes vehicles for which all of the following features are common:
  - permissible laden mass,
  - nominal traction drive power,
  - the largest number of seats,
  - type and sort of transmission,
  - type and sort of devices operating under traction voltage, current collectors,
     redundant protection devices for mains circuits,
  - type and sort of basic auxiliary equipment (converters, heating, auxiliary propulsion motors),
  - place of installation of the traction converters, traction motors, converters,
     auxiliary motors, components of the autonomous propulsion system,
  - power of the additional autonomous drive;

- 2) trolleybuses of which:
  - a) type includes vehicles for which all of the following features are common:
    - manufacturer,
    - factory type designation,
    - manufacturer of the traction drive,
    - main design considerations, including:
      - -- chassis and floor plate (obvious and basic differences),
      - -- number of trolleybus sections,
  - b) variant includes vehicles for which all of the following design features are common:
    - type and sort of traction drive (type of motor and traction converter),
    - number of motors and traction converters,
    - driving axles (number, position, kinematic link),
    - steering axles (number and location),
    - nominal supply voltage,
    - type of autonomous driving system (battery, capacitor, capacitor with batteries, diesel-electric, diesel-electric with batteries or diesel-electric with capacitor bank),
  - c) version includes vehicles for which all of the following features are common:
    - permissible laden mass,
    - nominal traction drive power,
    - total transmission ratio,
    - type and sort of devices operating under traction voltage, current collectors, redundant protection devices, electrodynamic braking resistors, linear contactors,
    - type and sort of auxiliary equipment, heaters, auxiliary propulsion motors, insulation status monitoring systems,
    - place of installation of the traction converters, traction motors, converters,
       auxiliary motors, components of the autonomous propulsion system,
    - power of the additional autonomous drive.

- **§ 4.** 1. When conducting approval tests, the technical service shall:
- 1) verify that the specifications and data contained in the information documents referred to in Annexes 6 and 7 to the Regulation are included in the information package and type approval certificates in respect of the regulatory acts required by the type approval procedure;
- 2) in the absence of certain items in the information documents referred to in Annexes 6 and 7 to the Regulation in the information package of the regulatory acts referred to in Annex 1 to the Regulation which are required for the type being tested, confirm or request the competent technical service to confirm that the specification and technical design of the item of equipment or part concerned conforms to the particulars contained in that information document;
- 3) compare the data and information contained in the information documents referred to in Annexes 6 and 7 to the Regulation, submitted by the manufacturer, with the scope of the requirements applicable to the type approval procedure;
- 4) verify that the type undergoing the approval tests is in conformity with the type shown in the information documents referred to in Annexes 6 and 7 to the Regulation;
- 5) on a tram or trolleybus selected for approval tests, conduct the appropriate checks and controls or ask the competent technical service to conduct the appropriate checks and controls, with regard to the installation of items of equipment or parts, in order to verify that the tram or trolleybus has been manufactured in accordance with the relevant data contained in the information package, in respect of the relevant type approval certificates provided by the manufacturer.
- 2. Following the type approval test of a tram or trolleybus, the technical service shall draw up in Polish the approval test report referred to in Article 20(3)(2) of the Act, bearing the signature of the head of the technical service or a person authorised by him.
- § 5. 1.In the case of a manufacturer's request for the issue or amendment of a national type approval certificate for a tram or trolleybus, the Director of TDT shall verify:
- 1) the completeness of the documents submitted in accordance with the list of required documents referred to in Article 20(3) of the Act;
- 2) the conformity of the information contained in the application for the issue or amendment of the national type approval certificate with the accompanying documents;

- 3) whether the application for the issue or amendment of the national type approval certificate has been signed by the manufacturer or by a person authorised to act on behalf of the manufacturer;
- 4) the correctness of the preparation of the information documents set out in Annexes 6 and 7 to the Regulation;
- 5) whether the approval tests have been conducted by the technical service;
- 6) whether the documents proving that the approval tests have been conducted have been signed by the head of the technical service or by a person authorised by him.
  - 2. For the issue, amendment, refusal or withdrawal of:
- 1) a national type approval certificate for a tram, the Director of TDT shall use the model national type approval certificate for a tram set out in Annex 3 to the Regulation;
- a national type approval certificate for a trolleybus, the Director of TDT shall use the model national type approval certificate for a trolleybus set out in Annex 4 to the Regulation;
- 3. For the issue, amendment, refusal or withdrawal of a national type approval certificate for a tram or trolleybus, the Director of TDT shall use the model of approval mark and method of numbering national type approval certificates for trams or trolleybuses set out in Annex 5 to the Regulation.
- § 6. 1. The technical service, having regard to the range of technical parameters specified in the documentation submitted by the manufacturer, shall determine the representative number of trams or trolleybuses that is necessary to verify, during the approval tests, the limit parameters within the type covered by the approval test procedure.
- 2. The technical service shall determine the conditions for the selection of trams or trolleybuses taking into account the minimum and maximum technical parameters in terms of mass, dimensions and pressures and completion as regards the items of equipment and parts which are set out in the information documents set out in Annexes 6 and 7 to the Regulation.
- § 7. 1. The scope and method of conducting approval tests for trams or trolleybuses and the detailed method of carrying out the national type approval procedure for trams or trolleybuses are laid down in Annex 2 to the Regulation.

- 2. The scope and method of conducting control of conformity of production in connection with the national type approval procedure for trams or trolleybuses are laid down in Annex 8 to the Regulation.
- 3. In the case of a control of conformity of production conducted by a technical service authorised to conduct such a control by the Director of TDT in accordance with Article 52(5) of the Act, the provisions of Annex 8 to the Regulation shall apply mutatis mutandis.
- § 8. The information documents used in the national type approval procedure for trams or trolleybuses accompanying the application for the issue or amendment of the national type approval certificate for a tram or trolleybus shall be drawn up:
- 1) in the case of type approval of a tram, in accordance with the model set out in Annex 6 to the Regulation the amendments made to that information document shall be clearly indicated by bold font in the case of an application for amendment of the type approval certificate where the amendment requires new approval tests to be conducted;
- 2) in the case of type approval of a trolleybus, in accordance with the model set out in Annex 7 to the Regulation the amendments made to that information document shall be clearly indicated by bold font in the case of an application for amendment of the type approval certificate where the amendment requires new approval tests to be conducted.
- § 9. 1. The model certificate of conformity used in the national type approval procedure for trams is set out in Annex 9 to the Regulation.
- 2. The model certificate of conformity used in the national type approval procedure for trolleybuses is set out in Annex 10 to the Regulation.
- 3. The model application for a national type approval certificate for a tram or trolleybus is set out in Annex 11 to the Regulation.
- 4. The model list of persons authorised to sign certificates of conformity for a tram or trolleybus is set out in Annex 12 to the Regulation.
- 5. The model declaration containing the trolleybus data and information necessary for the registration and records of a trolleybus is set out in Annex 13 to the Regulation.
- 6. The model list of persons authorised to sign the declaration containing the vehicle data and information necessary for the registration and records of a trolleybus is set out in Annex 14 to the Regulation.

 $\S$  10. This Regulation shall enter into force on the day following the date of its publication  $^{5)}$ 

### MINISTER FOR INFRASTRUCTURE

This Regulation was preceded by the Regulation of the Minister for Transport, Construction and Maritime Economy of 28 May 2013 on the type approval of trams and trolleybuses (Journal of Laws of 2015, item 38), which expires on the date of entry into force of the Act of 14 April 2023 on vehicle approval systems and their equipment (Journal of Laws, item 919).

Annexes to the Regulation of the Minister for Infrastructure of ... 2023 (Journal of Laws, item ...)

Annex 1

# LIST OF REQUIRED UN REGULATIONS APPLICABLE TO TYPE APPROVAL OF TRAMS

Item	Item of equipment	UN Regulation number	
1	Headlamps equipped with filament lamps (R2 and HS1)	16)	
2	Headlamps (sealed beam)	5 <sup>7)</sup>	
3	Headlamps equipped with filament lamps (H1, H2, H3, HB3, HB4, H7, and/or H8, H9, HIR1, HIR2 and/or H11)	88)	
4	Headlamps (halogen sealed beam)	319)	
5	Headlamps with gas-discharge light sources	9810)	
6	Headlamps with halogen lamps (H4)	2011)	
7	Headlamps with filament lamps or LED modules	112 <sup>12)</sup>	

<sup>&</sup>lt;sup>6</sup> Regulation No 1 of the Economic Commission for Europe of the United Nations (UN/ECE) – Uniform provisions concerning the approval of motor vehicle headlamps emitting an asymmetrical passing-beam and/or a driving beam and equipped with filament lamps of category R2 and/or HS1 (OJ L 177, 10.7.2010, p. 1).

<sup>7</sup> Regulation No 5 of the Economic Commission for Europe of the United Nations (UN/ECE) – Uniform provisions concerning the approval of power-driven vehicle's sealed beam headlamps (SB) emitting a European asymmetrical passing beam or a driving beam or both (OJ L 162, 29.5.2014, p. 1).

Regulation No 8 of the Economic Commission for Europe of the United Nations (UN/ECE) – Uniform provisions concerning the approval of motor vehicle headlamps emitting an asymmetrical passing beam or a driving beam or both and equipped with halogen filament lamps (H1, H2, H3, HB3, HB4, H7, H8, H9, HIR1, HIR2 and/or H11) (OJ L 185, 17.7.2010, p. 15).

<sup>9</sup> Regulation No 31 of the Economic Commission for Europe of the United Nations (UN/ECE) – Uniform provisions concerning the approval of power-driven vehicle's halogen sealed-beam headlamps (SB) emitting an asymmetrical passing beam or a driving beam or both (OJ L 185, 17.7.2010, p. 15).

<sup>10</sup> Regulation No 98 of the Economic Commission for Europe of the United Nations (UN/ECE) – Uniform provisions concerning the approval of motor vehicle headlamps equipped with gas-discharge light sources (OJ L 164, 30.6.2010, p. 92).

<sup>11</sup> Regulation No 20 of the Economic Commission for Europe of the United Nations (UN/ECE) – Uniform provisions concerning the approval of motor vehicle headlamps emitting an asymmetrical passing beam or a driving beam or both and equipped with halogen filament lamps (H4 lamps) (OJ L 177, 10.7.2010, p. 170).

<sup>12</sup> Regulation No 112 of the Economic Commission for Europe of the United Nations (UN/ECE) – Uniform provisions concerning the approval of motor vehicle headlamps emitting an asymmetrical passing-beam or a driving-beam, or both and equipped with filament lamps and/or light-emitting diode (LED) modules (OJ L 230, 31.8.2010, p. 264).

8	Filament lamps for use in approved lamp units	37 <sup>13)</sup>
9	Direction indicators*	6 <sup>14)</sup> alternatively 148 <sup>15)</sup>
10	Front and rear position lamps, stop-lamps and end-outline marker lamps	7 <sup>16)</sup> alternatively 148 <sup>10</sup>
11	Side-marker lamps	91 <sup>17)</sup> alternatively 148 <sup>10</sup>
12	Retro-reflecting devices	318)
13	Front fog lamps	19 <sup>19)</sup>
14	Rear fog lamps	38 <sup>20)</sup> alternatively 148 <sup>10</sup>
15	Reversing lamp	23 <sup>21)</sup> alternatively 148 <sup>10</sup>
16	Daytime running lamps	87 <sup>22)</sup> alternatively

<sup>&</sup>lt;sup>13</sup> Regulation No 37 of the Economic Commission for Europe of the United Nations (UN/ECE) – Uniform provisions concerning the approval of filament lamps for use in approved lamp units of power-driven vehicles and of their trailers (OJ L 213, 18.7.2014, p. 36).

<sup>14</sup> Regulation No 6 of the Economic Commission for Europe of the United Nations (UN/ECE) – Uniform provisions concerning the approval of direction indicators for power-driven vehicles and their trailers (OJ L 213, 18.7.2014, p. 1).

<sup>15</sup> Regulation No 148 of the Economic Commission for Europe of the United Nations (UN/ECE) – Uniform provisions concerning the approval of light-signalling devices (lamps) for power-driven vehicles and their trailers [2021/1719] (OJ L 347, 30.9.2021, p. 123).

<sup>16</sup> Regulation No 7 of the Economic Commission for Europe of the United Nations (UN/ECE) – Uniform provisions concerning the approval of front and rear position lamps, stop-lamps and end-outline marker lamps for motor vehicles (except motor cycles) and their trailers (OJ L 148, 12.6.2010, p. 1).

<sup>17</sup> Regulation No 91 of the Economic Commission for Europe of the United Nations (UN/ECE) – Uniform provisions concerning the approval of side-marker lamps for motor vehicles and their trailers (OJ L 164, 30.6.2010, p. 69).

<sup>18</sup> Regulation No 3 of the Economic Commission for Europe of the United Nations (UN/ECE) – Uniform provisions concerning the approval of retro-reflecting devices for power-driven vehicles and their trailers (OJ L 323, 6.12.2011, p. 1).

<sup>19</sup> Regulation No 19 of the Economic Commission for Europe of the United Nations (UN/ECE) – Uniform provisions concerning the approval of power-driven vehicle front fog lamps (OJ L 177, 10.7.2010, p. 113).

<sup>20</sup> Regulation No 38 of the Economic Commission for Europe of the United Nations (UN/ECE) – Uniform provisions concerning the approval of rear fog lamps for power-driven vehicles and their trailers (OJ L 148, 12.6.2010, p. 55).

<sup>21</sup> Regulation No 23 of the Economic Commission for Europe of the United Nations (UN/ECE) – Uniform provisions concerning the approval of reversing lamps and manoeuvring lamps for power-driven vehicles and their trailers (OJ L 237, 8.8.2014, p. 1).

<sup>22</sup> Regulation No 87 of the Economic Commission for Europe of the United Nations (UN/ECE) – Uniform provisions concerning the approval of daytime running lamps for power-driven vehicles (OJ L 164, 30.6.2010, p. 46).

		14810
17	Safety glazing	43 <sup>23)</sup>

<sup>\*)</sup> On bi-directional trams except those features attributed solely to uni-directional characteristics of motion of the vehicle.

<sup>&</sup>lt;sup>23</sup> Regulation No 43 of the Economic Commission for Europe of the United Nations (UN/ECE) – Uniform provisions concerning the approval of safety glazing materials and their installation on vehicles (OJ L 42, 12.2.2014, p. 1).

# SCOPE AND METHOD OF CONDUCTING APPROVAL TESTS FOR TRAMS OR TROLLEYBUSES AND DETAILED METHOD OF CARRYING OUT THE NATIONAL TYPE APPROVAL PROCEDURE FOR TRAMS OR TROLLEYBUSES

- 1. Scope and method of conducting approval tests for trams or trolleybuses:
- 1) preliminary assessment:
- a) a detailed examination by the technical service of the technical documentation concerning the type of tram or trolleybus provided by the manufacturer and, in the case of a trolleybus type, verification of the EU/EC type approval certificate of the vehicle or the national type approval certificate of the vehicle on the basis of which the trolleybus was built, together with the annexes,
- b) a detailed analysis of the technical documentation of the tram type or trolleybus type in terms of compliance with the technical regulations referred to in § 3 of the Regulation;
  - 2) approval test:
- a) verification by the technical service that the items of tram equipment or parts covered by the type approval procedure are made in accordance with the technical provisions referred to in § 3 of the Regulation and have the appropriate type approval certificates,
- b) verification by the technical service that the tram or trolleybus submitted for approval tests meets the technical conditions referred to in § 3 of the Regulation,
- c) after the approval tests have been conducted, the technical service shall draw up, in triplicate, an approval test report, of which one copy shall be kept by the technical service in its documentation and two copies shall be issued to the manufacturer.
  - 2. Detailed method of carrying out the national type approval procedures:
  - 1) for trams:
- a) the technical service shall perform the following actions:
  - -measurement of the external dimensions of the tram,
  - -measurement of the static contact forces exerted on the track by individual axles of a fully loaded tram,
  - -measurement of the sound level emitted outside the tram at a standstill,

- -measurement of the sound level emitted outside the tram in motion,
- -measurement of the sound level of the warning signal,
- -measurement of illumination inside the tram, in the doors and in the space in front of the doors,
- -measurement of braking distance at a speed of 30 km/h for brakes: service, sudden, emergency and safety,
- -parking brake performance test,
- -in a trailer tram, checking the braking system in the event of the detachment of the tram from the formation,
- -checking the functionality and operation of the manoeuvring dashboard to drive backwards, if applicable,
- -checking the operation and performance of available brakes when driving backwards,
- -checking that at least the emergency and parking brakes can be applied independently of the electronic controller,
- -checking if it is equipped with a device improving the coefficient of adhesion between the wheel and the rail,
- -measurement of the location of external lights on the tram,
- -checking equipment with external lights, their operation, electrical connections and controls,
- -checking the operation of the block on moving with open doors,
- -checking the operation of the driver's safety device,
- -checking the possibility of driving backwards,
- -checking the protection of the electrical installation against access by passengers and bystanders,
- -checking the protection of the electrical installation against mechanical damage, corrosion and flooding,
- -checking access to the low-voltage electrical circuit breaker,
- -checking that the electrical installation is equipped with protection in the event of a short circuit,
- -checking the performance of the brakes in the emergency operating conditions of the overhead contact line,

- -performing resistance measurements and dielectric insulation strength tests of wiring,
- -performing resistance measurements and dielectric insulation strength tests of apparatus,
- -checking the protective connections between the electrical mass of the tram body and the rail network and measuring the resistance of these connections,
- -checking the connections of the electric masses of individual sections in multi-section trams and the possibility of connecting electric masses of trams intended to work in multiple units,
- -measurement of the resistance between exposed elements made of conductive materials in the interior and the protective return circuit or tram structure,
- -checking the operation of dependencies in trams with electrical installation with capacitive elements or other energy sources and trams equipped with an autonomous driving system,
- -voltage measurement on the power side (on the collector) during actual driving on the urban network for trams adapted to return energy to the overhead contact line,
- -test drive,
- -checking the required tram equipment,
- -in trams intended to work in multiple units checking the guard of intercarriage couplings,
- -checking the equipment of the driver's station,
- -checking the passenger compartment equipment,
- -checking the marking of the edges of the steps,
- -checking the number of doors, their location, measuring the length of the passenger space closed on one side, measuring the width of the passageway, checking the required number of passenger flow lines,
- -checking the adaptation of at least one door to the needs of persons with disabilities,

- -at the entrance doors, checking the operation of the passenger trapping protection systems, mechanical opening and closing, emergency opening, individual opening, buttons for persons with disabilities, warning signal,
- -measurement of the force required for the emergency opening of the door,
- -measurement of the force required to activate the lever mechanism incorporating the safety brakes,
- -measurement of the passenger trapping force in the doors,
- -checking the method of opening the windows and manufacture of the front and rear windows,
- -checking the marking of the glazing,
- -measurement of the light transmission coefficient in windscreens,
- -checking the manufacture, number and method of marking emergency exits and control of access to them by means of an appropriate template,
- -control of the placement of handrails and handles by means of an appropriate check,
- -measurement of the gap dimensions in the floor in the joint area,
- -checking the guards in the joint area,
- -measurement of electromagnetic disturbances radiated into the environment,
- -checking, after the test drives, that there are no leakages of consumables,
- b) the technical service shall carry out an analysis of the following documents:
  - -information document used in the national type approval procedure for trams in accordance with Annex 6 to the Regulation,
  - -technical and movement documentation of the tram, which also includes the limit values of the wear of individual elements,
  - -the operating instructions for the tram,
  - -instructions for lifting and re-railing the tram,
  - -certificates confirming fire safety for compliance with PN-K-02511:2000 or PN-EN 45545-2:2021-01 for non-metallic materials used in the interior of the tram,

- -certificates confirming the manufacture of electrical cables in the interior from materials free from halogens,
- -calculation of the kinematic gauge of the tram,
- -approval certificates for the exterior lights used,
- -approval certificates for the glazing used,
- -diagrams of protective connections between the electrical mass of the tram body and the rail network,
- -description of the operation of the driver's safety device,
- -description of the operation of the driving locking system,
- -description of the operation of the door mechanisms and the protections used against trapping of the passenger,
- -records from the insulation strength tests of electrical sub-assemblies conducted by the manufacturers of these sub-assemblies,
- -documents proving the manufacturer's ability to ensure the manufacture of further trams conforming to the approved type;

# 2) for trolleybuses:

- a) the technical service shall perform the following actions:
  - -measurement of the sound level emitted by the trolleybus at a standstill,
  - -checking and measuring the dielectric insulation of the handrail and floor in the entrance door area,
  - -checking the protections used for live electrified parts and parts on which dangerous voltage may occur in the event of failure of the basic insulation, against access to them by passengers, bystanders and the driver.
  - -checking the protection of the electrical installation against mechanical damage, corrosion and flooding,
  - -checking the method used to disable the low-voltage control system,
  - -checking the functioning of the emergency disconnection of the mains electrical installation from the circuit of the current collectors,
  - -dielectric insulation tests of mains-voltage devices,
  - -dielectric insulation tests of devices powered by a three-phase auxiliary voltage 400 V and separated 24 V,

exists,

- -checking the redundant protections used in the mains installation, autonomous, if any, three-phase auxiliary 400 V and separated 24 V,
- -checking the operation of the signalling of the presence of dangerous voltage on the body,
- -checking the operation of the function that automatically disconnects the mains installation of the trolleybus from the circuit of the current collectors or from the overhead contact line if dangerous voltage is detected on the body for situations where the entrance doors remain open, -checking the operation of voltage decay signalling in the overhead contact line or in an autonomous power source, where such a source
- -checking the functioning of dependencies autonomous driving, for a trolleybus with an autonomous driving system,
- -checking the emergency operation of the steering support pump in the event of a voltage decay in the overhead contact line,
- -measurements of the braking deceleration with an electrodynamic service brake of 30 km/h,
- -checking the functioning of the electrodynamic brake in the full range of driving speed,
- -checking the functioning of the electrodynamic service brake priority over the start-up,
- -checking the operation of the drive when driving with overhead contact line power,
- -checking the functioning of the propulsion while driving with an autonomous source of energy, if any,
- -measurements of voltage levels in the current collector circuit during electrodynamic braking,
- -voltage measurements on elements mounted on the roof with a degree of protection less than IP2X when the collectors are disconnected from the mains,
- -measurements of electromagnetic disturbances emitted into the environment by the trolleybus at standstill and in motion,

- -checking the installation and ventilation conditions of the traction battery, if any,
- -checking the functioning of the dependency resulting in the automatic disconnection of the autonomous power source from the electrical installation when the low-voltage electrical installation is switched off,
- -measurements of static contact force of current collectors on the overhead contact line,
- -checking the freedom of movement of the trolleybus within the limits (+4.5 m, -4.5 m) from the longitudinal axis of symmetry of the overhead contact line,
- -checking the operation of the automatic pulling system of the current collectors in the event of their derailment,
- -checking the system blocking the possibility of the trolleybus moving with any pair of entrance doors open,
- b) the technical service shall carry out an analysis of the following documents:
  - -information document used in the national type approval procedure for trolleybuses in accordance with Annex 7 to the Regulation,
  - -technical and movement documentation of the trolleybus electrical equipment, together with diagrams of electrical circuits powered by mains and auxiliary voltages, including schematic diagrams of the dielectric insulation system of electrical equipment powered by mains and auxiliary voltages,
  - -the operating instructions for the trolleybus,
  - -documents proving the manufacturer's ability to ensure the manufacture of subsequent trolleybuses conforming to the approved type.

#### **MODEL**

#### NATIONAL TYPE APPROVAL CERTIFICATE FOR A TRAM

(maximum format: A4 (210 x 297 mm))



Dyrektor

Transportowego Dozoru Technicznego

ul. Puławska 125, 02-707 Warszawa

+48 22 490 29 02

info@tdt.gov.pl

Director of

**Transportation Technical Supervision** 

Pulawska Str. 125, 02-707 Warsaw

Stamp of the Director of

Transportation Technical

Supervision

# concerning<sup>1)</sup>:

- the issue of a type approval of a tram,
- amendments to the type approval of a tram,
- refusal of the type approval of a tram,
- withdrawal of the type approval of a tram,

issued pursuant to Art. 15(1)(5) of the Act of 14 April 2023 on approval systems for vehicles and their equipment (Journal of Laws, item 919).

Type approval certificate number:
Reason for the amendment <sup>2)</sup> :
0.1. Brand:
0.2. Type:

<sup>&</sup>lt;sup>1)1)</sup> Delete as appropriate.

<sup>&</sup>lt;sup>2)</sup> Fill in if applicable.

0.3. Commercial design	ation	
0.4. Name and address	of the manufacturer:	
0.5. Type of tram:		
0.6. Type of bodywork:		
0.13. Restrictions <sup>3)</sup>		
On the basis of the re	sult of the approval test cond	ucted and confirmed in the technical
service's approval test r	eport, the undersigned certifies	the conformity of the data contained in
the type approval certific	cate and in the information doc	rument with the results of the approval
tests.		
Issue of approval/Refus	al of approval/Withdrawal of ap	pproval <sup>1)4)</sup>
(place)	(signature)	(date)

### Annexes:

- 1. Information document used in the national type approval procedure for trams.
- 2. Approval test report issued by the technical service.
- 3. List of persons authorised to sign the certificate of conformity for a tram, including their personal data: name and surname, position held and specimen signature.

 $<sup>^{3)}</sup>$  Fill in if there are restrictions on the use of the tram or when the item of equipment or part of the tram performs its function only in conjunction with other parts of the tram.

<sup>4)</sup> The reasons for the refusal or withdrawal of approval shall be given.

#### Annex 4

#### **MODEL**

# NATIONAL TYPE APPROVAL CERTIFICATE FOR A TROLLEYBUS

(maximum format: A4 (210 x 297 mm))



Dyrektor

Transportowego Dozoru Technicznego

ul. Puławska 125, 02-707 Warszawa

+48 22 490 29 02

info@tdt.gov.pl

Director of

**Transportation Technical Supervision** 

Pulawska Str. 125, 02-707 Warsaw

Stamp of the Director of

Transportation Technical

Supervision

# concerning<sup>1)</sup>:

.1 •	r .	1	C	. 11 1
— tha icciia ai	t a fund '	annrowal (	nt a	trollowhiic
– the issue of	ιαινυς	αυυιυναι ι	лα	u one v ous.

- amendments to the type approval of a trolleybus,
- Refusal of the type approval of a trolleybus,
- Withdrawal of the type approval of a trolleybus,

issued pursuant to Art. 15(1)(6) of the Act of 14 April 2023 on approval systems for vehicles and their equipment (Journal of Laws, item 919).

Type approval certificate number:
Reason for the amendment <sup>2)</sup> :
0.1. Brand:
0.2. Type:

0.3. Commercial designation	ion	
0.4. Name and address of	the manufacturer:	
0.5. Type of bodywork:		
0.10. Restrictions <sup>3)</sup>		
service's approval test rep	,	d confirmed in the technical conformity of the data contained in ent with the results of the approval
Issue of approval/Refusal	of approval/Withdrawal of appro	val <sup>1),4)</sup>
(place)	(signature)	(date)

#### Annexes:

- 1. Information document used in the national type approval procedure for trolleybuses.
- 2. Approval test report issued by the technical service.
- 3. List of persons authorised to sign the certificate of conformity for a trolleybus, containing their personal data: name and surname, position held and specimen signature.

<sup>1)</sup> Delete as appropriate.

<sup>2)</sup> Fill in if applicable.

<sup>3)</sup> Fill in if there are restrictions on the use of the trolleybus or when the item of equipment or part of the trolleybus performs its function only in conjunction with other parts of the trolleybus.

<sup>4)</sup> The reasons for the refusal or withdrawal of approval shall be given.

#### **MODEL**

# APPROVAL MARK AND METHOD OF NUMBERING NATIONAL TYPE APPROVAL CERTIFICATES FOR TRAMS OR TROLLEYBUSES

1. The national type approval certificate number for trams and trolleybuses shall consist of three sections separated by the '\*' mark.

Section 1: the symbol 'PL'.

Section 2: four-digit approval number (with zeros at the beginning if needed to make it a four-digit number).

Section 3: two-digit extension number (with zero at the beginning if needed to make it a two-digit number), slash (breaking), letter 'T'.

#### Example:

Second extension to the fourth national type approval certificate for a tram or trolleybus: PL\*0004\*02/T.

2. In the event of amendments to the information package for the type certificate for a tram or trolleybus, when assigning the certificate number, after the amendment number which remains unchanged, the Director of Transportation Technical Supervision shall add the following indication, depending on the number of amendments granted so far:

'Revision 1, 2, 3 ...' or the abbreviation 'Rev. 1, 2, 3 ...'.

- 3. Where, as part of the type approval procedure for trams or trolleybuses, in addition to the amendments referred to in paragraph 2:
- 1) further controls or tests were required;
- 2) the data or information contained in the type approval certificate for a tram or trolleybus has changed, with the exception of annexes,
- 3) new requirements for the type of tram or trolleybus subject to the approval procedure have entered into force
- when an amendment to a type approval certificate for a tram or trolleybus is issued, in section 3 of the certificate number, the Director of Transportation Technical Supervision shall specify the amendment number corresponding to the number of successive amendments already granted.

#### Annex 6

# INFORMATION DOCUMENT USED IN THE NATIONAL TYPE APPROVAL PROCEDURE FOR TRAMS

Drawings shall be made in the appropriate scale and degree of detail in A4 format or folded to this format. The photographs should provide appropriate details. If the equipment and parts have electronic control, this shall be described. Where other essential items of equipment that are not mentioned in the document are present, these elements shall be described at the discretion of the approval testing authority.

0. GENERAL DATA
0.1. Brand:
0.2. Type:
0.3. Commercial designation
0.4. Name and address of the manufacturer:
0.5. Type of tram:
0.6. Type of bodywork: single-section/multi-section <sup>1)</sup>
0.7. Places of mounting the statutory plates:
0.7.1. bodywork:
0.7.2. bogie:
0.7.3. engines/motors:
0.7.4. traction apparatus:
0.8. Location of tram identification number:
0.9. Drawings or photographs of a representative of the type:
0.10. Drawing of the tram with basic dimensions:
0.11. Adaptation to bi-directional motion:
0.12. Adaptation to multiple-unit driving:
0.13. Restrictions:

0.13.1. in the use of the tram:
0.13.2. an item of equipment or part of the tram which performs its function only in conjunction with other parts of the tram:
1. DIMENSIONS AND WEIGHTS
1.1. Track gauge: mm
1.2. Length of the tram: mm
1.3. Width of the tram: mm
1.4. Height of the tram to the highest point on the roof with the folded current collector <sup>2)</sup> : mm
1.5. Spacing of the pivot pins: mm
1.6. Distance between the axes of the joints: mm
1.7. Wheelbase of the bogies: mm
1.8. Front overhang: mm
1.9. Rear overhang: mm
1.10. Bumper height <sup>2)</sup> :
1.10.1. at the front: mm
1.10.2. at the rear: mm
1.11. Minimum clearance of non-adjustable elements <sup>2)</sup> :
1.11.1. of the tram body: mm
1.11.2. of the bogie: mm
1.12. Unladen mass of the tram: kg
1.13. Technically permissible maximum laden mass of the tram for the permissible
number of places or load capacity:kg
1.14. Maximum axle load on the track for the permissible number of places or load
capacity: kN
1.15. Drawings of the kinematic gauge of the tram for the straight section and curve with
a radius R = 25 m:
2. PROPULSION SYSTEM
2.1. Axle arrangement:
2.2. Number of bogies:
2.2.1. driving:

4	2.2.2. rolling:
7	2.3. Number: driving axles/all axles:/
7	2.4. Type of transmission:
7	2.5. Total transmission ratio:
2	2.6. Type of drive: powered by overhead contact line/powered by overhead contact line
with	autonomous driving system/powered by overhead contact line with autonomous
mano	euvring driving system/autonomous <sup>1)</sup>
2	2.7. Number of converters-propulsion groups:
2	2.8. Number of propulsion motors:
7	2.9. Nominal supply voltage, applies to tram powered by overhead contact
line: .	V
4	2.10. Braking with energy return to the overhead contact line: yes/no <sup>1)</sup>
7	2.11. Method of implementation of the protection against moving with open doors under
norma	al operating conditions:
7	2.12. Method of implementation of protection against activation by unauthorised
perso	ns:
3	3. ELECTRIC TRACTION MOTORS
3	3.1. Manufacturer:
3	3.2. Type:
3	3.3. Type: series/asynchronous/synchronous <sup>1)</sup>
3	3.4. Rated power: kW
3	3.5. Rated voltage: V
3	3.6. Rated current: A
3	3.7. Rated rotational speed: rpm
3	3.8. Cooling method:
3	3.9. Insulation strength: kV (50 Hz, 60 s).
2	4. MOUNTING OF THE TRAM BODY
4	4.1. Method of placing the body on bogies, chassis or axles:
4	4.2. Number of degrees of springing of the body:
4	4.3. Type of components for springing the body:
4	5. DRIVING AND ROLLING BOGIES (if applicable)
4	5.1. Driving bogie

5.1.1. Manufacturer: .....

5.1.2. Type:	5.1.2. Type:						
5.2. Rolling bogie,	5.2. Rolling bogie, if applicable						
5.2.1. Manufacture	5.2.1. Manufacturer:						
5.2.2. Type:	5.2.2. Type:						
6. WHEELS	**						
6.1. Design feature	s of the whee	1:					
6.2. Wheel diamete	er: new/maxin	num used:	1	mm			
7. BRAKING SYS	TEM						
7.1. Summary tabl	e – types of	brakes involve	ed during the typ	pes of braki	ng mentioned		
(insertion of the X mark	in the table	cell means tha	t during the type	e of braking	mentioned in		
the column header, the b	orake mention	ed in the row t	itle is involved).				
	Types of bra	king					
Types of brakes	service	emergency		parking	sudden		
	braking	braking	safety braking	braking	braking		
electrodynamic brake							
passive mechanical brake (spring)							
active mechanical brake							
track brake							
7.2. Additional de	scription and	notes for the	e table, e.g.: du	ring service	braking, the		
passive mechanical brak	te is activated	when the tram	reaches a speed	of 5 km/h:			
7.3. Method of im	plementation	of the braking	g condition in th	e event of o	detachment of		
the trailer tram:		•••••					
7.4. Track brake							
7.4.1. Manufacture	7.4.1. Manufacturer:						
7.4.2. Type:	7.4.2. Type:						
7.4.3. Type: non-split/segmented <sup>1)</sup>							
7.4.4. Rated supply voltage:V							

	7.4.5. Rated current:
	7.4.6. Clamping force at rated supply voltage: kN
	7.4.7. Operating gap between the brake contact surface and the rail: mm
	7.4.8. Number of track brakes:
	7.5. Mechanical brake (indicate separately for each type)
	7.5.1. Manufacturer:
	7.5.2. Type:
	7.5.3. Sort:
	7.5.4. Actuator:
	7.5.5. Type of release mechanism:
	7.5.6. Number of mechanical brakes:
	7.5.7. Placement of mechanical brakes:
	7.6. Braking in the event of the failure of the electronic braking system controller:
	7.6.1. Types of braking that can be activated independently of the electronic
con	troller:
	7.6.2. Method of implementing the emergency braking types mentioned in paragraph
7.6.	1.:
	7.7. Device for improving the coefficient of adhesion
	7.7.1. Manufacturer:
	7.7.2. Type:
	7.7.3. Brief technical description:
	8. BODYWORK
	8.1. Materials and methods used:
	8.2. Passenger entrance doors:
	8.2.1. Number:
	8.2.2. Effective width: mm
	8.2.3. Door drive:
	8.2.3.1. Manufacturer:
	8.2.3.2. Type:
	8.2.3.3. Type of protection against trapping of the passenger:
	8.2.3.4. Type of protection against unintentional opening:
	8.2.3.5. Description of the control:

	8.2.4. Individual opening by passengers:
	8.2.5. Emergency opening method:
	8.3. Driver entrance doors:
	8.3.1. Number:
	8.3.2. Effective width: mm
	8.3.3. Type of protection against unintentional opening:
	8.3.4. Control:
	8.3.5. Emergency opening method:
	8.4. Windscreen and other panes
	8.4.1. Windscreen
	8.4.1.1. Type of pane: toughened-glass/multi-layered <sup>1)</sup>
	8.4.1.2. Method of attachment to the bodywork:
	8.4.1.3. Type approval number(s):
	8.4.2. Other panes
	8.4.2.1. Type of pane: toughened-glass/multi-layered <sup>1)</sup>
	8.4.2.2. Approval number(s):
	8.4.3. Other glazing components
	8.4.3.1. Materials used:
	8.4.3.2. Type approval number(s):
	8.5. Windscreen wipers – brief technical description:
	8.6. Windscreen washer – brief technical description:
	8.7. Windscreen defrosting – brief technical description:
	8.7.1. Maximum electric power consumption: kW
	8.8. Rear-view mirrors or devices performing their functions, indicate for each mirror or
dev	ice.
	8.8.1. Figure(s) showing the position in relation to the bodywork of the tram.
	8.9. Driver's station – location and marking of controls, tell-tales and indicators,
dra	wings or photographs with a description of:
	8.10. Additional control panel at the end of the tram – location and marking of controls,
tell-	-tales and indicators, drawings or photographs with a description of:
	8.11. Surface area for standing passengers: m2
	8.12. Total permissible number of places or load capacity:

8.13. Number of seats:
8.13.1. for staff:
8.13.2. for passengers:
8.14. Number of standing places, with the standard 0.20 m²/person:
8.15. Number of emergency exits and their location, drawings or
photographs:
8.16. Largest and smallest floor height of the unloaded tram <sup>2)</sup> mm
8.17. Passenger compartment heating system:
8.17.1. manufacturer:
8.17.2. type:
8.17.3. supply voltage:V
8.17.4. maximum power consumption: kW
8.17.5. insulation strength between the mains circuit of the radiator and the housing at
the control inputs shorted to the housing: kV (50 Hz, 60 s)
8.18. Driver's station heating system:
8.18.1. manufacturer:
8.18.2. type:
8.18.3. supply voltage:V
8.18.4. maximum power consumption: kW
8.18.5. insulation strength between the mains circuit of the radiator and the housing at
the control inputs shorted to the housing: kV (50 Hz, 60 s)
8.19. Passenger compartment ventilation system – brief
description:
8.19.1. Maximum power consumption: kW
8.20. Passenger compartment lighting
8.20.1. Basic lighting - description with drawings or additional photographs, in
particular type, power, location of light points, mode of
activation:
8.20.2. Emergency lighting – description with drawings or additional photographs, in
particular type, power, location of light points, mode of
activation:

8.21. Combustible properties of materials used to equip the interior

8.21.1. Material(s) used for the ceiling		
8.21.1.1. Approval number(s) or test certificates:		
8.21.2. Material(s) used for luminaires and lampshades of ceiling lamps		
8.21.2.1. Approval number(s) or test certificates:		
8.21.3. Material(s) used for the lining of the side and rear walls		
8.21.3.1. Approval number(s) or test certificates:		
8.21.4. Material(s) used for floor lining		
8.21.4.1. Approval number(s) or test certificates:		
8.21.5. Material(s) used for upholstery coverings		
8.21.5.1. Approval number(s) or test certificates:		
8.21.6. Material(s) used for other purposes		
8.21.6.1. Approval number(s) or test certificates, if any:		
8.21.6.2. For previously unapproved or untested materials		
8.21.6.2.1. Basic material(s) and their purpose:		
8.21.6.2.2. Single-layer/multi-layer material1), number of layers <sup>1)</sup> :		
8.21.6.2.3. Type of cover:		
8.21.6.2.4. Maximum/minimum thickness: mm		
8.21.7. Components approved or tested as complete devices, e.g. seats, partitions		
8.21.7.1. Approval number(s) or test certificates:		
8.22. Statutory plates		
8.22.1. Location of the statutory plates and identification number - description with		
drawings.		
8.22.2. Photographs or drawings of a dimensioned and filled plate:		
8.22.3. Photographs or drawings of the identification number indicating the		
dimensions:		
8.22.4. Explanation of the designation of the sections of the identification		
number:		
8.23. Entrance and places for persons with disabilities:		
8.23.1. Entrance:		
8.23.1.1. location of the entrance for persons with		
disabilities:		
8.23.1.2. entrance height: mm		

8.23.1.3. entrance width: mm
8.23.1.4. solutions to facilitate the embarkation and disembarkation of persons with
disabilities:
8.23.2. Place for wheelchairs and children's pushchairs:
8.23.2.1. location:
8.23.2.2. number of places:
8.23.2.3. surface area of places for wheelchairs and children's
pushchairs: m2
8.23.2.4. method of protecting the wheelchair or pushchair from
moving:
8.23.3. Seats for persons with disabilities:
8.23.3.1. number of places:
8.23.3.2. location:
8.23.3.3. marking:
8.24. Technical devices facilitating access to the tram, e.g. ramps, lifts, if
any:
8.25. Electrical cables installed in the internal non-combustible structure of the body:
8.25.1. manufacturer:
8.25.2 type:
8.25.3. numbers of test certificates for halogen compounds:
9. EXTERIOR LIGHTING AND SOUND SIGNALING
9.1. Table of all exterior lights, including retro-reflectors: number, make, model,
approval mark, maximum intensity of main-beam headlamps, colour, indicator:
9.2. Arrangement of exterior lights, drawings or photographs indicating the
dimensions:
9.3. Audible warning signal:
9.3.1. manufacturer:
9.3.2. type:
9.3.3. type of audible warning signal:
9.3.4. number and location of devices:
9.3.5. rated supply voltage:
9.3.6. Sound level A: dB

	10. DRIVE AND DRAKING CONVERTER
	10.1. Manufacturer:
	10.2. Type:
	10.3. Type: DC pulse/pulse inverter <sup>1)</sup>
	10.4. Input operating voltage range: V.
	10.5. Type of controlled semiconductor devices used:
	10.6. Pulse frequency of controlled semiconductor devices:
	10.7. Continuous rated power: kVA
	10.8. Short-term continuous power: kVA in a time of: s
	10.9. Cooling method:
	10.10. Place of installation:
	10.11. Insulation strength between the mains circuits and the mounting frame or housing
of	the converter at the control inputs and outputs shorted to the
hous	ing: kV (50 Hz, 60 s).
	10.12. Braking resistor:
	10.12.1. manufacturer:
	10.12.2. type:
	10.12.3. continuous rated power: kW
	10.12.4. maximum power: kW in a time of: s
	10.12.5. place of installation:
	10.12.6. cooling method:
	10.12.7. insulation strength between the current circuit and the resistor mounting
fram	e: kV (50 Hz, 60 s).
	10.13. Mains filter choke
	10.13.1. manufacturer:
	10.13.2. type:
	10.13.3. rated current:
	10.13.4. place of installation:
	10.13.5. cooling method:
	10.13.6. insulation strength between the current circuit of the choke and the mounting
fram	e: kV (50 Hz, 60 s).

# 11. STATIC CONVERTER

	11.1. Manufacturer:
	11.2. Type:
	11.3. Number of converters installed:
	11.4. Input operating voltage:V
	11.5. AC output(s), if applicable:
	11.5.1. voltage:
	11.5.2. nominal power: kVA.
	11.5.3. is used to power:
	11.6. DC output(s):
	11.6.1. voltage:V
	11.6.2. nominal current:
	11.6.3. is used to power:
	11.7. Insulation strength between the mains terminals and the mounting frame or the
hou	sing of the converter – DC and AC outputs, as well as the control input and output shorted
to t	he housing: kV (50 Hz, 60 s).
	11.8. Insulation strength between AC output terminals and DC terminals – DC outputs
sho	rted to the mounting frame, if applicable:kV
(50	Hz, 60 s).
	11.9. Cooling method:
	11.10. Place of installation:
	12. ELECTRICAL INSTALLATION OF CIRCUITS POWERED BY THE
ΟV	ERHEAD CONTACT LINE
	12.1. Rated supply voltage: V
	12.2. Operating supply voltage:V
	12.3. Maximum supply voltage:V
	12.4. Pole connected to mass:
	12.5. Method of protective earthing of the body, provide a description with a
diag	gram:
	12.6. Redundant protections:
	12.6.1. functions of redundant protection in the traction circuit shall be performed
by:	
	12.7. Main redundant circuit breaker, where applicable:

12.7.1. manufacturer:
12.7.2. type:
12.7.3. sort:
12.7.4. rated voltage:V
12.7.5. rated current: A
12.7.6. rated short-circuit breaking capacity: kA
12.7.7. control voltage:V
12.7.8. type of control: electromagnetic/electric servo motor <sup>1)</sup>
12.7.9. insulation strength between the current circuit of the circuit breaker and the
control system: kV (50 Hz, 60 s).
12.7.10. insulation strength between the current circuit of the circuit breaker and the
base or housing: kV (50 Hz, 60 s).
12.8. Fuses of the propulsion groups, where applicable:
12.8.1. manufacturer:
12.8.2. type:
12.8.3. sort:
12.8.4. nominal voltage: V
12.8.5. nominal current:
12.9. Circuit breakers or contactors of the propulsion groups, where applicable:
12.9.1. manufacturer:
12.9.2. type:
12.9.3. sort:
12.9.4. function: disconnection of the propulsion group/disconnection and redundate
protection of the propulsion group <sup>1)</sup>
12.9.5. nominal voltage:V
12.9.6. nominal current:
12.9.7. rated short-circuit breaking capacity, as long as it acts as a redundar
protection: kA
12.9.8. control voltage:V
12.9.9. type of control: electromagnetic/electric servo motor <sup>1)</sup>
12.9.10. insulation strength between the current circuit of the circuit breaker and the
control system: kV (50 Hz, 60 s).

12.9.	11. insulation strength between the current circuit of the circuit breaker and the
base or hou	using: kV (50 Hz, 60 s).
12.10	. Contactors of the auxiliary circuits:
12.10	.1. manufacturer:
12.10	.2. type:
12.10	.3. sort:
12.10	.4. nominal voltage:V
12.10	.5. nominal current: A
12.10	.6. control voltage:V
12.10	.7. type of control: electromagnetic/electric servo motor <sup>1)</sup>
12.10	.8. insulation strength between the current circuit of the contactor and the control
system:	kV (50 Hz, 60 s)
12.10	.9. insulation strength between the current circuit of the contactor and the base or
housing:	kV (50 Hz, 60 s)
12.11	. Lightning arrester:
12.11	.1. manufacturer:
12.11	.2. type:
12.11	.3. sort:
12 11	.4. continuous operating voltage:
12.11	.5. voltage level of protection:
12.12	. Equipotential electrical bonding between the different body sections, if
applicable:	
12.13	. Protection against continued driving at too low voltage and undervoltage
protection:	
12.13	.1. minimum mains voltage at which the drive can be implemented: V
12.13	.2. mains voltage at which the traction circuit is disconnected: V
12.13	.3. minimum mains voltage at which auxiliary circuits operate:V
12.13	.4. mains voltage at which the auxiliary circuits are disconnected: V
12.14	. A system enabling energy return from the tram to the overhead contact line, if
applicable:	
12.14	.1. voltage on the mains filter capacitor at which the resistance braking resistor is
activated:	V

12.14.2	2. minimum mains voltage at which energy recovery is carried out:
12.14.3	3. method of blocking the energy return in the event of a decrease in the voltage
level in the	e mains below the level defined in paragraph 12.14.2: disconnection with
contactor/dis	sconnection with circuit breaker/blocking with semiconductor connector <sup>1)</sup>
13. EL	ECTRICAL CONTROL SYSTEM
13.1. C	Control voltage:V
13.2. B	atteries
13.2.1.	number, voltage and capacity of batteries: V/Ah
13.2.2.	place of installation:
13.3. C	Control devices: controllers, control panels, etc.
13.3.1.	type:
13.3.2.	supply voltage:V
13.3.3.	place of installation:
13.3.4.	cooling method:
13.3.5.	voltage strength of the insulation in relation to the controller housing (applies to
controllers b	ouilt in shields made of conductive materials): kV
(50 Hz, 60 s	
14. CO	UPLING DEVICES
14. Tov	wing coupling:
14.1. m	nanufacturer:
14.2. ty	/pe
14.3. so	ort
14.4. m	naximum tensile/compressive force: kN
14.5. h	eight of the coupling end axle <sup>2)</sup> mm
15. CU	RRENT COLLECTOR
15. Cu	rrent collector:
15.1. m	nanufacturer:
15.2. ty	pe:
15.3. so	ort:
15.4. co	ontrol: manual/automatic <sup>1)</sup>
15.5. no	ominal voltage:V
15.6. no	ominal current: A

15.7. maximum current: A
15.8. operating range <sup>2)</sup> : mm
15.9. static contact force on the overhead contact line in the operating
range: N
15.10. insulation strength between the current circuit (base) of the collector and the mass
of the tram: kV (50 Hz, 60 s).
16. OPERATIONAL DATA
16.1. Minimum permissible track curve levels: mm
16.2. Minimum permissible vertical curve of the track: mm
16.3. Average unloaded tram acceleration up to 30 km/h: m/s2
16.4. Maximum current consumption during start-up: A
16.5. Maximum reverse current flowing into the mains that may occur during a
regenerative braking, if applicable: A
16.6. Average braking parameters for the unloaded tram at a speed of 30 km/h:
16.6.1. service braking deceleration value: m/s2
16.6.2. emergency braking deceleration value: m/s2
16.6.3. sudden braking deceleration value: m/s2
16.6.4. safety braking deceleration value: m/s2
16.6.5. Sound level A outside while driving at 50 km/h: dB
16.7. Sound level A outside at standstill dB
16.8. Maximum speed: km/h
16.9. Electrodynamic braking traction characteristics for nominal supply voltage:
16.9.1. A diagram of the maximum braking force for the electrodynamic brake as a
function of speed, if applicable:
16.9.2. A current diagram as a function of the speed that can be returned by the tram to
the mains, with the maximum electrodynamic braking force, if
applicable:
17. AUTONOMOUS DRIVING SYSTEM OR ADDITIONAL ENERGY STORAGE
SYSTEM, if applicable
17.1. Type of autonomous driving system: battery-powered electric motors/capacitor-

 $powered\ electric\ motors/battery-and-capacitor-powered\ electric\ motors^{1)}$ 

17.1.1. purpose of the autonomous driving system, applies to trams powered by the
overhead contact line: for regular passenger service/for auxiliary emergency or manoeuvring
operation <sup>1)</sup>
17.2. Traction batteries, if applicable:
17.2.1. type of batteries:
17.2.2. capacity: Ah
17.2.3. voltage:
17.2.4. mass: kg
17.2.5. function: energy storage unit for autonomous driving only/energy storage unit
used only for network driving/energy storage unit for autonomous driving and energy storage
for network driving <sup>1)</sup>
17.2.6. place of installation:
17.2.7. ventilation method:
17.2.8. redundant protection of the batteries: fuses/fuses and circuit breaker <sup>1)</sup>
17.2.9. battery overheating protection, if applicable:
17.2.10. protection against too high voltage on the cells:
17.3. Traction capacitor bank, if applicable:
17.3.1. manufacturer:
17.3.2. type:
17.3.3. type of capacitor:
17.3.4. single capacitor bank capacity: F
17.3.5. maximum operating voltage of capacitor bank:
17.3.6. maximum operating current: charging/discharging the capacitor
bank: A
17.3.7. maximum permissible instantaneous current: charging/discharging the capacitor
bank: A
17.3.8. number of capacitor banks used:
17.3.9. total capacity of the system: F
17.3.10. maximum operating voltage of the capacitor bank system:
17.3.11. mass of the system: kg
17.3.12. used: for autonomous driving only/for network driving only/for autonomous
driving and as support during network driving <sup>1)</sup>

	17.3.13. place of installation:
	17.3.14. cooling method:
	17.3.15. redundant protection: fuses/fuses and circuit breaker <sup>1)</sup>
	17.3.16. protection against too high voltage level:
	17.3.17. insulation strength of the capacitor bank between the current circuit and the
hoı	using kV (50 Hz, 60 s)
	17.4. Converter working with the batteries, if applicable:
	17.4.1. manufacturer:
	17.4.2. type:
	17.4.3. nominal power:kVA
	17.4.4. type of controlled semiconductor devices used:
	17.4.5. pulse frequency of controlled semiconductor devices:
Hz	
	17.4.6. function: charging the traction battery/increasing the supply voltage of the
tra	ction converter during autonomous driving/charging and increasing the supply voltage of
the	traction converter during autonomous driving <sup>1)</sup>
	17.4.7. maximum battery charging current, if applicable:
	17.4.8. input voltage range during battery charging, if applicable: V
	17.4.9. output voltage range during battery charging, if applicable: V
	17.4.10. voltage range of the traction system and auxiliary circuits during autonomous
dri	ving, if applicable:V
	17.4.11. place of installation:
	17.4.12. cooling method:
	17.4.13. declared insulation strength between the mains circuits and the mounting frame
or l	housing of the converter: kV (50 Hz, 60 s).
	17.5. Converter working with the traction capacitor bank, if applicable:
	17.5.1. manufacturer:
	17.5.2. type:
	17.5.3. nominal power:kVA
	17.5.4. function of the converter: control of current and voltage charging/discharge
cur	rrent/increasing voltage at discharge <sup>1)</sup>
	17.5.5. type of controlled semiconductor devices used:

1	17.5.6. pu	lse frequency	of contro	lled semice	onductor dev	ices:	•••••	•••••
Hz.								
1	17.5.7. ma	ximum currei	nt during ca	pacitor bar	nk charging: .		A	
1	17.5.8.	maximum	current	during	capacitor	bank	discharging,	if
applic	able:				A			
1	17.5.9. ma	ximum charg	ing voltage	of capacito	or bank:		V	
1	17.5.10. pl	lace of installa	ation:					
1	17.5.11. co	ooling method	l:					
1	17.5.12. i	nsulation stre	ength betw	een the m	ains circuits	and the	mounting fram	e or
housin	ng of the c	converter:		kV (	(50 Hz, 60 s).			
1	17.6. Fuse	s of the auton	omous driv	ing circuits	s, if applicable	e:		
1	17.6.1. ma	nufacturer:						
1	17.6.2. typ	e:						
1	17.6.3. sor	t:						
1	17.6.4. noi	minal voltage	:		V			
1	17.6.5. noi	minal current:			A			
1	17.7. Circı	uit breaker of	the autonor	mous drivir	ng system, if a	applicable	<b>:</b> :	
1	17.7.1. ma	nufacturer:						
1	17.7.2. typ	e:						
1	17.7.3. sor	t:						
1	17.7.4. pla	ice of installat	ion of the o	circuit breal	ker:			
1	17.7.5. fur	nction: discon	nection of	the autono	mous system	/disconne	ction and redun	dant
protec	tion of the	e autonomous	circuit <sup>1)</sup>					
1	17.7.6. noi	minal voltage	:		V			
1	17.7.7. noi	minal current:		•••••	A			
1	17.7.8. rat	ed short-circu	it breaking	capacity, i	f applicable: .		A	
1	17.7.9. coi	ntrol voltage:			V			
1	17.7.10. ty	pe of control:						
1	17.7.11. iı	nsulation stre	ngth betwe	en the cur	rent circuit o	f the circ	cuit breaker and	the
contro	ol system:				kV (50 Hz,	60 s)		
1	17.7.12. iı	nsulation stre	ngth betwe	en the cur	rent circuit o	of the circ	cuit breaker and	the
base o	or housing				kV (50 Hz, 6	0 s).		

17.8. Hydraulic transmission, if applicable:
17.8.1 type:
17.8.2. manufacturer:
17.8.3. sort:
17.9. Mechanical transmission, if applicable:
17.9.1 type:
17.9.2. manufacturer:
17.9.3. sort:
17.9.4. number and gear ratios of individual gears:

17.10. The operating data of the autonomous driving system shall be reported according to paragraph 16, excluding paragraphs 16.4, 16.5 and, in the case of a propulsion system not using electric motors, excluding paragraph 16.9. In a situation where the tram during autonomous driving does not reach a maximum speed of 50 km/h, the sound level A during the movement shall be measured at an attainable speed close to the maximum speed, whereas in a situation where the tram during autonomous driving does not reach a maximum speed of 30 km/h, the decelerations of the different types of braking shall be measured from an attainable speed close to the maximum speed.

17.11. Indicative range: ...... km.

<sup>1)</sup> Delete as appropriate

<sup>2)</sup> All dimensions refer to the level of the rail head.

# INFORMATION DOCUMENT USED IN THE NATIONAL TYPE APPROVAL PROCEDURE FOR TROLLEYBUSES

Drawings shall be made in the appropriate scale and degree of detail in A4 format or folded to this format. The photographs should provide appropriate details. If the equipment and parts have electronic control, this shall be described. Where other essential items of equipment that are not mentioned in the description are present, these elements shall be described at the discretion of the approval testing authority.

n	١.	GE.	NΤ	וכו	$\Box$	Λ.	г 1	$\Box$	Λ -	ГΛ	
(	, ,	L TH.	IV	H.I	к	А		. ,	Α	ΙA	

U. GENERAL DATA
0.0.1. Type approval certificate/EU type approval certificate/EC type approval certificate number <sup>1)</sup> of the vehicle on the basis of which the trolleybus was built:
0.1. Brand:
0.2. Type:
0.3. Commercial designation
0.4. Name and address of the manufacturer:
0.5. Type of bodywork:
0.6. Places of mounting plates and markings relating to electrical equipment:
0.6.1. bodywork:
0.6.2. chassis:
0.6.3. engines/motors:
0.7. Location of the identification number:
0.8. Drawings or photographs of a representative of the type:
0.9. Drawing with basic dimensions:
0.10. Restrictions:
0.10.1. in the use of the trolleybus:
0.10.2. an item of equipment or part of the trolleybus which performs its purpose only in conjunction with other parts of the trolleybus:

#### 1. DIMENSIONS AND WEIGHTS

	1.1. Unladen mass: kg
	1.2. Permissible laden mass: kg
	1.3. Permissible load capacity: kg
	1.4. Number of seats for passengers:
	1.5. Nominal number of places:
	1.6. Individual axle loads with permissible load capacity: kN
	1.7. Length of the trolleybus with folded current collectors: mm
	1.8. Height of the trolleybus to the highest point on the roof with folded current
colle	ectors <sup>2)</sup> : mm
	2. PROPULSION SYSTEM
	2.1. Number: driving axles/all axles:/
	2.2. Number of traction motors:
	2.3. Total transmission ratio:
	2.4. Wheel diameter:
	2.5. Type of traction drive: resistance adjustable DC motor/DC motor with pulse
adju	stment/AC motor with pulse adjustment <sup>1)</sup>
	2.6. Nominal mains supply voltage: V
	2.7. Mains operating voltage:
	2.8. Number of drive and braking converters:
	2.9. Energy return system to the overhead contact line: yes/no <sup>1)</sup>
	2.10. Autonomous driving system: yes/no <sup>1)</sup>
	3. TRACTION MOTOR
	3.1. Manufacturer:
	3.2. Type:
	3.3. Type: series/series shunt/asynchronous/synchronous <sup>1)</sup>
	3.4. Place of installation of the motors (motor):
	3.5. Rated power: kW
	3.6. Rated voltage:V
	3.7. Rated current: A
	3.8. Rated rotational speed: rpm
	3.9. Cooling method:

	3.10. Insulation strength between the windings and the motor
body	: kV (50 Hz, 60 s).
	3.11. Insulation strength between the motor body and trolleybus mass (II-
degr	ee):kV (50 Hz, 60 s).
	3.12. Mass: kg
	4. DRIVE AND BRAKING CONVERTER, if applicable
	4.1. Manufacturer:
	4.2. Type:
	4.3. Type: DC pulse/pulse inverter <sup>1)</sup>
	4.4. Input operating voltage of the converter: V.
	4.5. Control range of the output voltage of the converter, applies to the
inve	rter: V
	4.6. Type of controlled semiconductor devices used:
	4.7. Pulse frequency of controlled semiconductor
devi	ces: Hz
	4.8. Continuous rated power: kVA
	4.9. Short-term continuous power:
of:	S
	4.10. Cooling method of the converter:
	4.11. Place of installation of the converter:
	4.12. Insulation strength between the mains circuits and mounting frame or housing of
the c	onverter (I-degree): kV (50 Hz, 60 s)
	4.13. Insulation strength between the mounting frame or the housing of the converter
and	the trolleybus mass (II-degree): kV (50 Hz, 60 s).
	4.14. Braking resistor:
	4.14.1. type:
	4.14.2. continuous rated power: kW
	4.14.3. maximum power: kW in a time of: s
	4.14.4. place of installation:
	4.14.5. cooling method:
	4.14.6. insulation strength between the current circuit and the resistor mounting frame
(I-de	egree):

4.14./. insulation strength between the resistor mounting frame and the trolleybus mass
(II-degree): kV (50 Hz, 60 s).
4.15. Mains filter choke:
4.15.1. rated current:
4.15.2. place of installation:
4.15.3. cooling method:
4.15.4. insulation strength between the current circuit of the choke and the mounting
frame: kV (50 Hz, 60 s).
4.15.5. insulation strength between the choke mounting frame and the trolleybus mass
(II-degree): kV (50 Hz, 60 s).
5. RESISTANCE ADJUSTABLE CONTROL, if applicable
5.1. Type of start-up actuator: electromechanical/electronic <sup>1)</sup>
5.2. Number of start-ups and dilution rates of the traction motor field:
5.3. Number of braking steps:
5.4. Place of installation of the start-up and braking resistors:
5.5. Method of ventilation of the start-up and braking
resistors:
5.6. Contactors for closing resistance sections and shunting:
5.6.1. manufacturer:
5.6.2. type:
5.6.3. sort:
5.6.4. rated voltage:V
5.6.5. rated switching current: A
5.6.6. control voltage:V
5.6.7. insulation strength between the current circuit of the contactors and the control
terminals: kV (50 Hz, 60 s)
5.6.8. insulation strength between the current circuit of the contactors and the base or
housing: kV (50 Hz, 60 s)
5.7. Start-up contactor(s):
5.7.1. manufacturer:
5.7.2. type:
5.7.3. sort:

5.7.4. rated voltage:
5.7.5. rated switching current: A
5.7.6. control voltage:
5.7.7. Trigger setting range, if applicable: A
5.7.8. insulation strength between the current circuit of the contactor and the control
terminals: kV (50 Hz, 60 s)
5.7.9. insulation strength between the current circuit of the contactor and the base or
housing: kV (50 Hz, 60 s)
5.8. Automatic start-up relay:
5.8.1. manufacturer:
5.8.2. type:
5.8.3. type: electromagnetic/electronic <sup>1)</sup>
5.8.4. function: overload protection during start-up/overload protection and start-up
current adjustment <sup>1)</sup>
5.8.5. operating current of the protection:
5.8.6. current adjustment range, if applicable: A
5.8.7. rated current circuit voltage:
5.8.8. rated current:
5.8.9. control voltage: V
5.8.10. insulation strength between the current circuit of the relay and the control
system: kV (50 Hz, 60 s)
5.8.11. insulation strength between the current circuit of the relay and the base or
housing: kV (50 Hz, 60 s)
6. CURRENT COLLECTORS
6.1. Manufacturer:
6.2. Type:
6.3. Material from which the bar is made:
6.4. Current collector head:
6.4.1. Manufacturer:
6.4.2. Type:
6.4.3. Method of attachment to the bar:

6.5. Control: manual/semi-automatic with automatic lowering/semi-automatic with
automatic lowering and lifting at network points adapted for this operation/automatic1)
6.6. Nominal voltage: V
6.7. Nominal current:
6.8. Maximum current:
6.9. Pulling mechanism in case of derailment: mechanical drum with a spring
drive/mechanical drum with an electric drive/pneumatic actuator/electric servo motor <sup>1)</sup>
6.10. Lifting mechanism of the collector (if applicable): pneumatic actuator/electric
servo motor <sup>1)</sup>
6.11. Operating range in the vertical plane: m <sup>2)</sup>
6.12. Operating range in the horizontal plane (measured from the longitudinal axis of
symmetry of the trolleybus): m
6.13. Static contact force in the operating range:
6.14. Insulation strength between the current circuit and the mounting base of the
collector: kV (50 Hz, 60 s).
6.15. Insulation strength between the mounting base of the collector and the mass of the
bodywork: kV (50 Hz, 60 s).
7. MAINS-VOLTAGE AND THREE-PHASE AUXILIARY ELECTRICAL
INSTALLATION
7.1. Mains reverser – protection system for proper polarisation of the voltage supplying
traction circuits, if applicable:
7.1.1. Type: contactor/power electronic <sup>1)</sup>
7.1.2. Scope of operation: allows only energy consumption at any mains polarity/enables
energy consumption at any mains polarity and brake energy return at one defined mains
polarity/enables energy consumption and return at any mains polarity <sup>1)</sup>
7.1.3. Place of installation:
7.2. Types of circuit breakers to disconnect the electrical installation of the trolleybus
from the circuit of the current collectors:
7.2.1. pole (+):
7.2.2. pole (–):
7.3. Redundant protections:

7.3.1. functions of redundant protection in the traction circuit shall be perform	ned
by:	
7.4. Redundant circuit breaker, if applicable:	
7.4.1. manufacturer:	
7.4.2. type:	
7.4.3. sort:	
7.4.4. place of installation of the circuit breaker:	
7.4.5. nominal voltage:	
7.4.6. nominal current:	
7.4.7. rated short-circuit breaking capacity:	
7.4.8. triggering: uni-directional (for fixed current direction)/bi-directional <sup>1)</sup>	
7.4.9. control voltage:V	
7.4.10. type of control: electromagnetic/electric servo motor <sup>1)</sup>	
7.4.11. insulation strength between the current circuit of the circuit breaker and	the
control system: kV (50 Hz, 60 s).	
7.4.12. insulation strength between the current circuit of the circuit breaker and the b	ase
or housing: kV (50 Hz, 60 s).	
7.5. Circuit breaker(s) disconnecting the electrical installation of the trolleybus from	the
circuit of the current collectors:	
7.5.1. manufacturer:	
7.5.2. type:	
7.5.3. sort:	
7.5.4. place of installation:	
7.5.5. nominal voltage:	
7.5.6. nominal current:	
7.5.7. control voltage:	
7.5.8. type of control:	
7.5.9. insulation strength between the current circuit of the circuit breaker and	the
control system: kV (50 Hz, 60 s)	
7.5.10. insulation strength between the current circuit of the circuit breaker and the b	ase
7.5.10. insulation strength between the current circuit of the circuit breaker and the bor housing:	ase

7.6.1. manufacturer:
7.6.2. type:
7.6.3. sort:
7.6.4. nominal voltage: V
7.6.5. nominal current:
7.7. Fuses for propulsion groups, where applicable:
7.7.1. manufacturer:
7.7.2. type:
7.7.3. sort:
7.7.4. nominal voltage: V
7.7.5. nominal current:
7.8. Circuit breakers or contactors of the propulsion groups, where applicable:
7.8.1. manufacturer:
7.8.2. type:
7.8.3. sort:
7.8.4. function: disconnection of the propulsion group/disconnection and redundant
protection of the propulsion group <sup>1)</sup>
7.8.5. nominal voltage: V
7.8.6. nominal current:
7.8.7. rated short-circuit breaking capacity, as long as it acts as a redundant
protection: kA
7.8.8. triggering, if applicable: uni-directional, for fixed current direction/bi-directional <sup>1)</sup>
7.8.9. control voltage: V
7.8.10. type of control: electromagnetic/electric servo motor <sup>1)</sup>
7.8.11. insulation strength between the current circuit of the circuit breaker and the
control system: kV (50 Hz, 60 s).
7.8.12. insulation strength between the current circuit of the circuit breaker and the base
or housing: kV (50 Hz, 60 s).
7.9. Contactors of the auxiliary circuits:
7.9.1. manufacturer:
7.9.2. type:
7.9.3. sort:

7.9.4	4. nominal voltage: V
7.9.5	5. nominal current: A
7.9.6	6. control voltage:V
7.9.7	7. type of control: electromagnetic/electric servo motor <sup>1)</sup>
7.9.8	3. insulation strength between the current circuit of the circuit breaker and the
control sy	stem: kV (50 Hz, 60 s)
7.9.9	9. insulation strength between the current circuit of the circuit breaker and the base
or housing	g: kV (50 Hz, 60 s)
7.10	. Lightning arrester:
7.10	.1. manufacturer:
7.10	.2. type:
7.10	.3. sort:
7.10	.4. continuous operating voltage:V
7.10	.5. voltage protection level:V
7.10	.6. place and method of installation:
7.10	.7. method of obtaining double insulation of the lightning arrester base from
trolleybus	s mass:
7.10	.8. voltage strength of the lightning arrester insulation relative to the mounting
frame:	kV (50 Hz, 60 s).
7.10	.9. voltage strength of the lightning arrester mounting frame relative to the
trolleybus	s mass: kV (50 Hz, 60 s).
7.11	. Mains-voltage system cables:
7.11	.1. manufacturer:
7.11	.2. type:
7.11	.3. nominal voltage:V
7.11	.4. insulation strength kV (50 Hz, in a time of s).
7.12	. Passenger compartment heating system
7.12	.1. manufacturer:
7.12	.2. type:
7.12	.3. supply voltage: V
7.12	.4. maximum power consumption: kW

7.12.5. insulation strength between the heating element and the radiator mounting frame
(I-degree): kV (50 Hz, 60 s)
7.12.6. insulation strength between the radiator mounting frame and the radiator housing
(II-degree, applies to radiators powered directly from the overhead contact
line): kV (50 Hz, 60 s)
7.12.7. place of installation of the radiators
7.13. Heating system for the driver's station
7.13.1. manufacturer:
7.13.2. type:
7.13.3. supply voltage:V
7.13.4. maximum power consumption: kW
7.13.5. insulation strength between the heating element and the radiator mounting frame
(I-degree): kV (50 Hz, 60 s).
7.13.6. insulation strength between the radiator mounting frame and the radiator housing
(II-degree, applies to radiator powered directly from the overhead contact
line): kV (50 Hz, 60 s).
7.14. Passenger compartment ventilation system, brief description, in the case of mains
circuit supply, the strength of both degrees of insulation shall be
provided:
7.14.1. supply voltage:V
7.14.2. maximum power consumption: kW
7.15. Components used to dampen electromagnetic disturbances, if applicable, the
manufacturer, type of filter, capacity of capacitors used in the filter, capacity of additional
damping capacitors, location and method of connecting additional damping capacitors
dielectric insulation strength of capacitors.
7.16. List of electrically connected masses of mains-powered intermediate devices
where such connections are present:
7.17. Protection against continued driving at too low voltage and undervoltage
protection:
7.17.1. minimum mains voltage at which the drive can be implemented: V
7.17.2. mains voltage at which the traction circuit is disconnected: V
7.17.3. minimum mains voltage at which the auxiliary circuits operate: V

7.17.4. mains voltage at which the auxiliary circuits are disconnected: V
7.18. Energy return system to the overhead contact line, if applicable:
7.18.1. voltage on the mains filter capacitor at which the resistance braking resistor is
activated:V
7.18.2. minimum mains voltage at which energy recovery may be carried
out: V
7.18.3. method of blocking the energy return in the event of a decrease in the voltage in
the mains below the value defined in paragraph 7.18.2: disconnection with
contactor/disconnection with circuit breaker/blocking with semiconductor connector1)
7.19. Rated voltage of the three-phase auxiliary system
7.20. Three-phase auxiliary system cables (if applicable):
7.20.1. manufacturer:
7.20.2. type:
7.20.3. nominal voltage:
7.20.4. insulation strength: kV (50 Hz, in a time of s)
7.21. Contactors, circuit breakers and fuses used in the three-phase auxiliary system,
specify the manufacturer, type, sort, nominal voltage and insulation
strength:
7.22. Dielectric insulation strength of the three-phase, galvanically integral auxiliary
system relative to the mains voltage
system: kV (50 Hz, 60 s).
7.23. Dielectric insulation strength of the three-phase, galvanically integral auxiliary
system relative to the trolleybus mass: kV (50 Hz, 60 s).
8. STATIC CONVERTER
8.1. Manufacturer:
8.2. Type:
8.3. Place of installation:
8.4. Input operating voltage:
8.5. AC output(s):
8.5.1. voltage:
8.5.2. nominal power:kVA

8.6. DC output(s):
8.6.1. voltage: V
8.6.2. nominal current:
8.6.3. is used to power:
8.7. Insulation strength between the mains terminals and the mounting frame or housing
of the converter – DC and AC outputs shorted to the
housing: kV (50 Hz, 60 s)
8.8. Insulation strength between the AC output terminals and the mounting frame of
housing at all other terminals shorted to the housing: k
(50 Hz, 60 s).
8.9. Insulation strength between DC output terminals and housing at all other terminal
shorted to the housing, if applicable: kV (50 H
60 s)
8.10. Insulation strength between the mounting frame or the housing of the converte
and the trolleybus mass: $kV$ (50 Hz, 60 s).
8.11. Insulation between the mains input and AC output/outputs <sup>1)</sup> : 1-degree/2-degree <sup>1)</sup> .
8.12. Cooling method:
9. COMPRESSOR UNIT
9.1. Auxiliary compressor drive motor.
9.1.1. Manufacturer:
9.1.2. Type:
9.1.3. Type: DC commutator brush/DC brushless with electron
commutator/asynchronous <sup>1)</sup>
9.1.4. Place of installation of the motor:
9.1.5. Rated power: kW
9.1.6. Rated voltage:V
9.1.7. Rated current: A
9.1.8. Rated rotational speed: rpm
9.1.9. Cooling method:
9.1.10. Motor body-winding insulation strength: kV (50 Hz, 60 s)

9.1.11. Motor body insulation strength – trolleybus mass, applies to motors powered
from a source without double insulation in relation to circuits powered directly by traction
voltage: kV (50 Hz, 60 s).
9.2. Compressor.
9.2.1. Manufacturer:
9.2.2. Type:
9.2.3. Sort:
9.2.4. Operating range of rotational speed: rpm
10. POWER STEERING SYSTEM
10.1. Mode of propulsion of the power steering system mechanism: auxiliary electric
motor/from the traction motor shaft and auxiliary electric motor <sup>1)</sup>
10.2. Auxiliary motor
10.2.1. Manufacturer:
10.2.2. Type:
10.2.3. Type: DC commutator brush/DC brushless with electronic
commutator/asynchronous <sup>1)</sup>
10.2.4. Place of installation of the motor:
10.2.5. Rated power: kW
10.2.6. Rated voltage:V
10.2.7. Rated current:
10.2.8. Rated rotational speed: rpm
10.2.9. Cooling method:
10.2.10. Motor body-winding insulation strength: kV (50 Hz, 60 s)
10.2.11. Motor body insulation strength - trolleybus mass, applies to motors powered
from a source without double insulation in relation to circuits powered directly by traction
voltage: kV (50 Hz, 60 s).
10.2.12. Method of implementation of emergency operation of the motor of the support
pump after the occurrence of voltage decay in the overhead contact line:
10.3. Support pump.
10.3.1. Manufacturer:
10.3.2. Type:
10.3.3. Mode of propulsion: from the auxiliary motor/from the traction motor shaft <sup>1).</sup>

10.3.4. Operating range of rotational speed: rpm
11. MOTOR FOR THE COOLING FAN OF THE ELECTRIC TRACTION
EQUIPMENT SYSTEM (if applicable)
11.1. Manufacturer:
11.2. Type:
11.3. Sort:
11.4. Place of installation of the motor:
11.5. Rated power: kW
11.6. Rated voltage:V
11.7. Rated current: A
11.8. Rated rotational speed: rpm
11.9. Motor body-winding insulation strength: kV (50 Hz, 60 s)
11.10. Motor body insulation strength - trolleybus mass, applies to motors powered
from a source without double insulation in relation to circuits powered directly by traction
voltage: kV (50 Hz, 60 s).
12. CONTROL SYSTEM OF MAINS-VOLTAGE DEVICES
12.1. Supply method of control circuits: from a separating converter(s) providing
galvanic separation from a bus control system not separated from the mass of the
trolleybus/mixed with control circuits powered by both the separating converter and the
control system of the bus not separated from the mass of the trolleybus/from the bus system
not separated from the mass of the trolleybus/from the bus system separated from the mass of
the trolleybus (two-wire bus system) <sup>1)</sup>
12.2. Separate electrical control system, if applicable:
12.2.1. power supply: from the output of the separated electrostatic converter described
in paragraph 8/from an additional separate separating converter <sup>1)</sup>
12.2.2. additional separating converter(s) made as separate from the main static
converter, if applicable;
12.2.2.1. manufacturer:
12.2.2.2. type:
12.2.2.3. rated power:kW
12.2.2.4. input voltage:
12.2.2.5 output voltage:

12.2.2.	<ol><li>cooling method</li></ol>	:				
12.2.2.	7. place of installa	tion:				
12.2.2.	8. insulation strei	ngth betwee	en the sepa	arated input and or	utput terminals, i	input
terminals	shorted	to	the	converter	frame	or
housing:				kV (50 H	z, 60 s).	
12.2.3.	Signal separation	between the	e non-sepa	rated electric bus sy	stem and the sepa	arate
traction con	trol system:					
12.2.3.	1. type of separato	ors:				
12.2.3.	2. sort of separato	rs:				
12.2.3.	3. number of sepa	rators used:				
12.2.3.	4. voltage strength	of separato	ors:	kV (5	60 Hz, 60 s)	
12.2.4.	insulation strengt	h of the sep	arated, gal	vanically integral to	raction control sy	stem
in relation to	the mains voltag	e system:	•••••		kV (50	) Hz,
60 s).						
12.2.5.	insulation strengt	h of the sep	arated, gal	vanically integral to	raction control sy	stem
relative to th	ne mass of the troll	leybus:		kV (50 H	z, 60 s).	
12.3. C	Control devices: co	ntrollers, et	c.			
12.3.1.	type:					
12.3.2.	supply voltage:	•••••		······································	I	
12.3.3.	supply method: fi	om a separa	ated system	/from a non-separa	ted bus system <sup>1)</sup>	
12.3.4.	method of obtain	ing insulation	on in relation	on to the mains ins	tallation, if the de	evice
is powered b	y a separate syste	m, the meth	od of obtai	ning and the voltag	e strength of at le	ast a
single insula	ation from mains c	circuits shall	be provide	ed, whereas if the d	evice is powered	by a
non-separate	ed system, the me	ethod of ob	taining and	I the voltage streng	gth of at least do	ouble
insulation fr	om the mains circ	uits shall be	provided:			
12.3.5.	place of installation	on:	•••••			
12.3.6.	cooling method: .					
12.4. S	eparated control s	ystem cable	s, if applica	able:		
12.4.1.	manufacturer:		•••••		•••••	
12.4.2.	type:					
12.4.3.	nominal voltage:			V		

12.4.4. insulation strength: kV (50 Hz, in a time
of s)
13. BUS CONTROL SYSTEM
13.1. Control voltage:
13.2. Number, voltage and capacity of batteries: V/Ah
13.3. Pole connected to mass:
13.4. Location of the battery switch: V
14. DESCRIPTION OF THE INSULATION OF THE ENTRANCE DOOR AREA
(the description should include how the handrails located in the door area have been
insulated from the trolleybus mass, the type and basic parameters of the dielectric liner
located in the door area or on the entrance steps)
15. DEVICE FOR DETECTING HAZARDOUS POTENTIAL ON THE BODY OR
OTHER ADDITIONAL DEVICES FOR MONITORING THE INSULATION STATUS OF
DEVICES OPERATING UNDER MAINS VOLTAGE
15.1. Device for detecting hazardous potential on the body.
15.1.1. Manufacturer:
15.1.2. Type:
15.1.3. Type of measurement system:
15.1.4. Supply voltage:V
15.1.5. The voltage level at which the signalling alerts the appearance of potential
between the bodywork and the road surface: V
15.1.6. Method of signalling the occurrence of hazardous potential between the
bodywork and the road surface:
15.1.7. Place of installation:
15.2. Additional device for monitoring the insulation status.
15.2.1. Manufacturer:
15.2.2. Type:
15.2.3. Type: intermediate mass insulation status meter/discharge current detector <sup>1)</sup>
15.2.4. Supply voltage:V

15.2.5. The place of con	nection to the monitored of	circuits, in the case of the	ne device for		
testing the insulation state of intermediate masses, all monitored masses or intermediate					
circuits shall be provided, in the case of the insulation status meter or voltmeters, the internal					
resistance of the measuring	instrument, the dielectric	strength of the insul	ation of the		
measuring device, the type and level of the measurement voltage used and the time of the					
individual	measurements	shall	be		
provided:					

15.2.6. Signalling threshold(s) for lowering of the insulation level, discharge current to the ground, setting of permissible minimum insulation values for intermediate masses or permissible voltage levels for intermediate masses in relation to the trolleybus body:

#### 16. OPERATIONAL DATA

- 16.1. Average declared unloaded acceleration up to 30 km/h: ..... m/s2
- 16.2. Maximum speed: ..... km/h

- 16.5. Average declared electrodynamic braking deceleration without load at 30 km/h: ...... m/s2
  - 16.6. Sound level A outside at standstill: .......... dB
  - 16.7. Electrodynamic braking traction characteristics for nominal supply voltage:
- 16.7.1. Diagram of the maximum braking force for the electrodynamic brake as a function of speed: ......
- 16.7.2. A current diagram as a function of the speed that can be returned by the trolleybus to the mains, with the maximum electrodynamic braking force, if applicable: .....
- 17. AUTONOMOUS DRIVING SYSTEM OR ADDITIONAL ENERGY STORAGE SYSTEM, if applicable
- 17.1. Power source for autonomous driving, if applicable: batteries/capacitors/batteries and capacitors/generator set driven by a combustion engine<sup>1)</sup>
- 17.1.1. Purpose of the autonomous driving system: regular passenger service/emergency passenger service/emergency driving or manoeuvring over a very short distance<sup>1)</sup>

	17.2. Traction batteries, if applicable:
	17.2.1. type of batteries:
	17.2.2. capacity: Ah
	17.2.3. voltage:
	17.2.4. mass: kg
	17.2.5. place of installation:
	17.2.6. ventilation method:
	17.2.7. redundant protection: fuses/fuses and circuit breaker <sup>1)</sup>
	17.2.8. overheating protection (if applicable):
	17.2.9. protection against too high voltage level on the cells:
	17.2.10. Voltage strength of the base insulation on which the batteries are mounted in
relati	on to the trolleybus mass: kV (50 Hz, 60 s).
	17.3. Traction capacitor bank, if applicable:
	17.3.1. manufacturer:
	17.3.2. type:
	17.3.3. sort of capacitors:
	17.3.4. capacitor bank capacity:F
	17.3.5. maximum operating voltage of a single capacitor bank:
	17.3.6. maximum operating current: charging/discharging the capacitor
bank:	:
	17.3.7. maximum permissible instantaneous current: charging/discharging the capacitor
bank:	:
	17.3.8. number of capacitor banks used:
	17.3.9. capacitor bank total capacity: F
	17.3.10. mass:
	17.3.11. Capacitor bank used: for autonomous driving only/for network driving only/for
auton	nomous driving and as support during network driving <sup>1)</sup>
	17.3.12. place of installation:
	17.3.13. ventilation method:
	17.3.14. redundant protection of the capacitors: fuses/fuses and circuit breaker <sup>1)</sup>
	17.3.15. protection against too high voltage level:

17.3.10. Insulation strength between the current circuit of the capacitor bank and the
capacitor housing (I-degree): kV (50 Hz, 60 s)
17.3.17. insulation strength between the capacitor bank housing and trolleybus mass (II-
degree) kV (50 Hz, 60 s)
17.4. Converter separating and charging the batteries:
17.4.1. manufacturer:
17.4.2. type:
17.4.3. nominal power:
17.4.4. type of controlled semiconductor devices used:
17.4.5. pulse frequency of controlled semiconductor devices: Hz.
17.4.6. maximum battery charging current:
17.4.7. input voltage range during battery charging: V
17.4.8. output voltage range during battery charging: V
17.4.9. place of installation:
17.4.10. cooling method:
17.4.11. insulation strength between the mains circuits and the housing (mounting
frame) of the converter at terminals designed to work with the traction battery shorted to the
housing (I-degree): kV (50 Hz, 60 s).
17.4.12. insulation strength between the mounting frame or the housing of the converter
and the trolleybus mass (II-degree):kV (50 Hz, 60 s).
17.5. Converter working with the traction capacitor bank, if applicable:
17.5.1. manufacturer:
17.5.2. type:
17.5.3. nominal
power:kVA
17.5.4. function of the converter: control of current and voltage charging/discharge
current/increasing voltage at discharge <sup>1)</sup>
17.5.5. type of controlled semiconductor devices used:
17.5.6. pulse frequency of controlled semiconductor devices:
17.5.7. maximum current during capacitor bank charging:
17.5.8. maximum current during capacitor bank discharging, if
applicable: A

17.5.9. maximum charging voltage of capacitors: V						
17.5.10. place of installation:						
17.5.11. cooling method:						
17.5.12. insulation strength between the mains circuits and the mounting frame or						
housing of the converter: kV (50 Hz, 60 s).						
17.5.13. insulation strength between the mounting frame or the housing of the converter						
and the trolleybus mass:						
17.6. Generator set powered by a combustion engine, if applicable:						
17.6.1. manufacturer:						
17.6.2. type:						
17.6.3. place of installation:						
17.6.4. combustion engine:						
17.6.4.1. manufacturer:						
17.6.4.2. type:						
17.6.4.3. type of combustion engine: four-stroke petrol/four-stroke diesel <sup>1)</sup>						
17.6.4.4. cylinder capacity: cm3						
17.6.4.5. number and arrangement of cylinders:						
17.6.4.6. maximum power: kW						
17.6.4.7. rotational speed corresponding to the maximum power: rpm						
17.6.4.8. maximum torque:						
17.6.4.9. rotational speed corresponding to the maximum						
torque: rpm						
17.6.4.10. cooling method: liquid/air <sup>1)</sup>						
17.6.4.11. exhaust emission standard:						
17.6.5. Fuel tank						
17.6.5.1. manufacturer:						
17.6.5.2. type:						
17.6.5.3. fuel tank capacity:						
17.6.5.4. place of installation of the fuel tank:						
17.6.5.5. type approval number:						
17.6.6. Generator:						
17.6.6.1. manufacturer:						

	17.6.6.2. type:
	17.6.6.3. sort:
	17.6.6.4. nominal power: kVA
	17.6.6.5. nominal voltage:
	17.6.6.6. Nominal revolutions: rpm
	17.6.6.7. Maximum revolutions: rpm
	17.6.6.8. maximum power: kVA available in the time specified by the
man	ufacturer
	17.6.6.9. voltage control method:
	17.6.6.10. output voltage control range:
	17.6.6.11. insulation strength of the generator body-winding: kV (50 Hz, 60 s)
	17.6.6.12. cooling method:
	17.6.7. sound level A at standstill when the generator set is switched on: dB
	17.7. Fuses of the autonomous driving circuits, if applicable:
	17.7.1. manufacturer:
	17.7.2. type:
	17.7.3. sort:
	17.7.4. nominal voltage:
	17.7.5. nominal current:
	17.8. Circuit breaker(s) of the autonomous driving system, if applicable:
	17.8.1. manufacturer:
	17.8.2. type:
	17.8.3. sort:
	17.8.4. place of installation of the circuit breaker(s):
	17.8.5. function: disconnection of the autonomous system/disconnection and redundant
prote	ection of the autonomous circuit <sup>1)</sup>
	17.8.6. nominal voltage:
	17.8.7. nominal current:
	17.8.8. rated short-circuit breaking capacity, if applicable:
	17.8.9. control voltage: V
	17.8.10. type of control:

17.8.11. insulation strength l	between the c	urrent ci	rcuit of	the circuit	breaker	and t	the		
control system:		kV	(50 Hz,	60 s)					
17.8.12. insulation strength l	between the c	urrent ci	rcuit of	the circuit	breaker	and t	the		
base or housing:		kV	(50 Hz	, 60 s)					
17.9. Traction parameters:	17.9. Traction parameters:								
17.9.1. Maximum speed of the	17.9.1. Maximum speed of the empty trolleybus: km/h								
17.9.2. Average acc	celeration	of th	he e	empty	trolleybus	<b>;</b>	to		
30 km/h: m/s2									
17.9.3. Average declared bra	aking decelera	ation of	the emp	ty trolleyb	us at a s	peed	of		
30 km/h: m/s2 (where the	30 km/h: m/s2 (where the trolleybus during autonomous driving does not reach a								
maximum speed of 30 km/h, the measurement of electrodynamic braking acceleration and									
deceleration shall be carried out a	according to th	e speed	obtained	d and at an	attainabl	e spe	ed		
close to the maximum speed).									
17.9.4. Indicative range in urban traffic:									

<sup>1)</sup> Delete as appropriate.

<sup>2)</sup> All dimensions refer to the surface of the roadway.

# SCOPE AND METHOD OF CONDUCTING CONTROL OF CONFORMITY OF PRODUCTION IN CONNECTION WITH THE NATIONAL TYPE APPROVAL PROCEDURE FOR TRAMS OR TROLLEYBUSES

- 1. Control of conformity of production referred to in Article 52 of the Act of 14 April 2023 (Journal of Laws, item 919), hereinafter referred to as 'control', conducted by the Director of Transportation Technical Supervision, hereinafter referred to as the 'Director of TDT', consists of two stages:
- 1) preliminary assessment;
- verification of the projects and methods ensuring the conformity of production of the tram or trolleybus, items of equipment or parts, hereinafter referred to as 'products', with the type covered by the approval certificate.
- 2. As part of the preliminary assessment, the Director of TDT shall verify the existence of a quality management system at the manufacturer.
- 2.1. When determining the scope of the preliminary assessment, the Director of TDT shall take into account:
- the manufacturer's documentation confirming compliance with the harmonised standard ISO 9001 or an equivalent harmonised standard that meets the general requirements of the preliminary assessment;
- 2) documentation of the vehicle manufacturer's assessment of the quality management system of the manufacturer of the products in accordance with one or more industrial specifications meeting the requirements of the standard referred to in subparagraph 1.
- 2.2. When the Director of TDT takes into account, for the purposes of the preliminary assessment, the documentation submitted by the manufacturer in accordance with the standard referred to in paragraph 2.1(1) during the control, the Director of TDT shall determine with the manufacturer how to communicate any amendments to the scope and validity of that documentation.
- 2.3. The preliminary assessment carried out prior to the issue of an approval certificate for a tram or trolleybus shall not require a re-assessment carried out for the purpose of issuing a type approval certificate for an item of equipment or part fitted to that type. In such a case,

the scope of the preliminary assessment should cover the manufacturing facilities of the vehicle manufacturer and activities related to the assembly of the tram or trolleybus which were not covered by the preliminary assessments carried out prior to the issue of the type approval certificate for the item of equipment or part of that tram or trolleybus.

- 3. As part of the verification of the projects and methods put in place by the manufacturer to ensure the conformity of production of the products with the type covered by the approval certificate, the Director of TDT shall:
- 1) check with the manufacturer:
  - a) the method of functioning of the production process of the products:
    - production planning,
    - keeping and storing production records,
    - overseeing the various stages of the production process,
    - storage and transport of finished products,
  - b) the mode of operation of the product delivery system:
    - the existence of a supplier assessment system,
    - warehousing and control of deliveries,
    - the use of product markings for effective and timely delivery,
    - procedures for product complaints,
  - c) the existence of a system of testing and internal controls of manufactured products, ensuring:
    - checking the conformity of the vehicle's completion with the data contained in the type approval certificate for the tram or trolleybus,
    - access to R & D and control equipment, including the method of identification and verification of such equipment,
    - documenting and making available the results of tests and internal controls of products, inter alia through control plans,
    - analysing the results of internal tests and controls with a view to verifying and ensuring that the manufacturer maintains the same level of product production, while taking into account advances in technology and industrial production,
    - an effective process to eliminate non-conformities identified as a result of internal tests and controls,

- an effective process to eliminate and withdraw defective devices from production, including the use of the markings of such devices;
- 2) determine with the manufacturer the period of storage of the results of tests and internal controls on devices conducted by that manufacturer.
- 4. The Director of TDT shall agree on the date of the control with the entity being controlled, hereinafter referred to as 'the controlled entity'.
- 5. The Director of TDT shall, no later than 14 days before the date of commencement of the control activities, notify the controlled entity of:
- 1) the scope of the control;
- 2) the estimated duration of the control.
- 6. Controls shall be conducted in the presence of a representative of the controlled entity.
- 7. After conducting the control, the Director of TDT shall draw up a record which shall include:
- 1) the name and registered office of the controlled entity;
- 2) date of the control;
- 3) a list of the representatives of the controlled entity containing their personal data: name, surname and position held;
- 4) personal data of the persons conducting the control: name, surname and position held;
- 5) a list of the documents, procedures, production processes, facilities, premises or equipment controlled;
- 6) a description of the observations;
- 7) non-conformities found;
- 8) comments about the control submitted by the controlled entity and preventive or corrective actions proposed by the controlled entity;
- 9) the deadline for the implementation and verification of preventive or corrective actions;
- 10) annexes indicating the name of each of them, including written declarations, explanations, calculations and other documents provided by the controlled entity;
- 11) the date and place of drawing up the record, signatures of the persons conducting the control and of the controlled entity.
  - 8. The record shall be drawn up in triplicate, of which:
- 1) one copy is intended for the controlled entity;

- 2) one copy is intended for the Director of TDT;
- 3) one copy is intended for the technical service as part of its type approval documentation.

### MODEL

# CERTIFICATE OF CONFORMITY USED IN THE NATIONAL TYPE APPROVAL PROCEDURE FOR TRAMS

maximum format: A4 (210 x 297 mm) or folded to this format

(company stamp or letterhead)					
I, the undersigned,					
(surname and first name)					
certify that the tram:					
0.1. Brand:					
0.2. Type:					
Variant <sup>1)</sup> :					
Version <sup>2)</sup> :					
0.3. Commercial designation					
0.4. Name and address of the manufacturer:					
0.5. Type of tram:					
0.6. Type of bodywork:					
0.7. Places of mounting the statutory plates:					
0.7.1. bodywork:					
Tram identification number:					
0.8. Location of tram identification number:					

0.9. Restrictions <sup>3)</sup> :						
1.12. Unladen mass of the tram: kg						
1.13. Technically permissible maximum laden mass of the tram for the permissib						
number of places or load capacity: kg						
1.14. Maximum axle load on the track for the permissible number of places or load						
capacity: kN						
2.6. Type of drive: powered by overhead contact line/powered by overhead contact line						
with autonomous driving system/powered by overhead contact line with autonomou						
manoeuvring driving system/autonomous <sup>4)</sup>						
8.12. Total permissible number of places or load capacity:						
8.13.2. Number of seats for passengers <sup>5)</sup> :						
12.1. Rated supply voltage:V						
corresponds to the type described in type approval certificate No of of						
(place) (date)						
(signature of the manufacturer's authorised representative) (position)						

<sup>1)</sup> Certificates of conformity shall be issued on paper with security in the form of at least coloured graphics or a watermark corresponding to the manufacturer's identification mark.

<sup>2)</sup> On the first page of the duplicate certificate of conformity, the word 'duplicate' shall be added.

<sup>3)</sup> Fill in if applicable.

<sup>4)</sup> Fill in if there are restrictions on the use of the tram or when the item of equipment or part of the tram performs its function only in conjunction with other parts of the tram.

<sup>5)</sup> Delete as appropriate.

#### *MODEL*

# CERTIFICATE OF CONFORMITY USED IN THE NATIONAL TYPE APPROVAL PROCEDURE FOR TROLLEYBUSES

maximum format: A4 (210 x 297 mm) or folded to this format

(company stamp or letterhead)						
I, the undersigned,						
(surname and first name)						
certify that the trolleybus:						
0.1. Brand:						
0.2. Type:						
Variant <sup>1)</sup> :						
Version <sup>2)</sup> :						
0.3. Commercial designation						
0.4. Name and address of the manufacturer:						
0.5. Type of bodywork:						
0.6. Places of mounting plates and markings relating to electrical equipment:						
0.6.1. bodywork:						
Vehicle identification number:						
0.7. Location of the identification number:						
0.8. Restrictions <sup>3)</sup> :						
1.1. Unladen mass: kg						

	1.2. Permissible laden mass: kg							
	1.4. Number of seats for passengers:							
	1.5. Nominal number of places:							
	1.6. Individual axle loads with permissible load capacity:	kN						
,	2.6. Nominal mains supply voltage:V							
,	2.10. Autonomous driving system: yes/no <sup>4)</sup>							
	17.1. Power source for autonomous driving (if applicable): batte	eries/capacitors/batteries						
and c	apacitors/generator set driven by a combustion engine <sup>5)</sup>							
corres	sponds to the type described in type approval certificate No	of						
	(place)	(date)						
(signature of the manufacturer's authorised representative) (position)								

<sup>&</sup>lt;sup>1)</sup> Certificates of conformity shall be issued on paper with security in the form of at least coloured graphics or a watermark corresponding to the manufacturer's identification mark.

On the first page of the duplicate certificate of conformity, the word 'duplicate' shall be added.

<sup>&</sup>lt;sup>3)</sup> Fill in if applicable.

<sup>&</sup>lt;sup>4)</sup> Fill in if there are restrictions on the use of the trolleybus or when the item of equipment or part of the trolleybus performs its function only in conjunction with other parts of the trolleybus.

<sup>&</sup>lt;sup>5)</sup> Delete as appropriate.

### MODEL

APPLICATION FOR A NATIONAL TYPE APPROVAL CERTIFICATE FOR A TRAM OR TROLLEYBUS
(place, date)
(name and address of the manufacturer)
(the authority competent to issue the type approval certificate)
I apply for the issue/amendment <sup>1)</sup> of a national type approval certificate:
– for a tram <sup>1)</sup>
– for a trolleybus <sup>1)</sup>
1. Type approval test report number
indiriber
2. Vehicle
type
3. Name and address of the
manufacturer
(legible manufacturer's signature)

1) Delete as appropriate.

Annex 12

### MODEL

# LIST OF PERSONS AUTHORISED TO SIGN CERTIFICATES OF CONFORMITY FOR A TRAM OR TROLLEYBUS

name and surname	position	specimen signature
		(legible manufacturer's signature)

#### MODEL

## DECLARATION CONTAINING THE TROLLEYBUS DATA AND INFORMATION NECESSARY FOR THE REGISTRATION AND RECORDS OF A TROLLEYBUS

Declaration containing the trolleybus data and information necessary for the registration and records of a  $trolleybus^{1)}$ 

I declare the addition	nal data and info	ormation on t	the vehic	ele necessary	y for registration		
and records under the regulations in force in the Republic of Poland, which corresponds in all							
respects to the type described in the EC vehicle type approval certificate/EU vehicle type							
approval certificate/nati	ional vehicle	type app	proval	certificate <sup>2</sup>	No		
of, which was recognised by the authority competent							
to recognise this	certificate by	y means	of	decision	No		
of							

Item	Vehicle data and information	Specification
1	VIN or bodywork, chassis or frame number	
2	Туре	
3	Subtype	
4	Purpose <sup>3)</sup>	
5	Year of manufacture	
6	Unladen mass [kg]	

<sup>)</sup> Not applicable to an incomplete vehicle. Delete as appropriate.

<sup>)</sup> If applicable.

7	Permissible load capacity [kg]		
8	Maximum permissible axle load [kl	N]	
9	Permissible laden mass of the vehic	le [kg]	
10	Permissible laden mass of the unit of [kg]	f vehicles	
11	Technically permissible maximum lof the trailer with brake [kg] <sup>4)</sup>	aden mass	
12	Other <sup>5)</sup>		
(place)		(date)	
(legible manufacturer's signature)		(position)	

<sup>)</sup> Not applicable to tractor unit.
) Refers to other data and information deemed relevant by the vehicle manufacturer.

### MODEL

# LIST OF PERSONS AUTHORISED TO SIGN THE DECLARATION CONTAINING THE VEHICLE DATA AND INFORMATION NECESSARY FOR THE REGISTRATION AND RECORDS OF A TROLLEYBUS

name and surname	position	specimen signature
	(le	gible manufacturer's signature)